

Organization, Correlation, and First Results of CONT11

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Abstract

In the second half of September 2011 the continuous VLBI campaign CONT11 was observed. Thirteen globally distributed VLBI stations collected data for fifteen consecutive days without interruption. In addition an ultra-rapid dUT1 determination demonstration was performed on the baseline Onsala–Tsukuba yielding dUT1 estimates with very low latency during the ongoing CONT11 campaign. In this paper we describe the planning and organization of the campaign, give an overview of the correlation effort, and conclude with first analysis results from the campaign.

1. Introduction

The continuous VLBI campaign 2011 (CONT11) was observed with a network of thirteen stations in the period from 15–29 September 2011 (see Figure 1). CONT11 constitutes the sixth

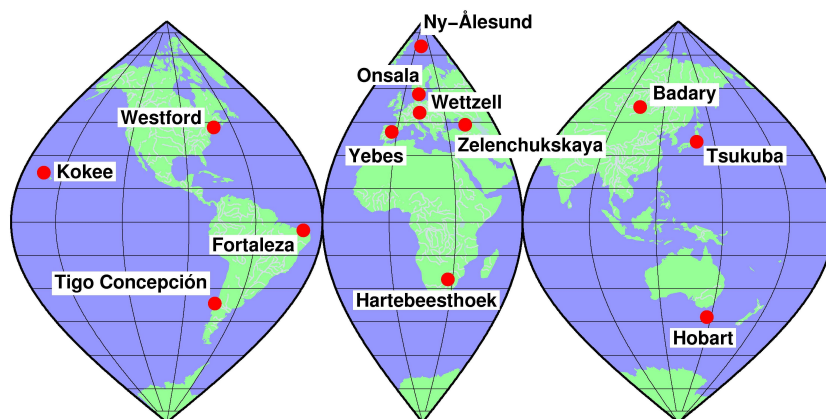


Figure 1. Observational network of thirteen stations of the CONT11 campaign.

continuous VLBI campaign following the successful observations of CONT94, CONT96, CONT02, CONT05, and CONT08. As in previous campaigns, CONT11 acquired state-of-the-art VLBI data

the ongoing CONT11 campaign and displayed on a dedicated Web page. Figure 3 shows the dUT1 estimates and the predicted values for the entire 15 days.

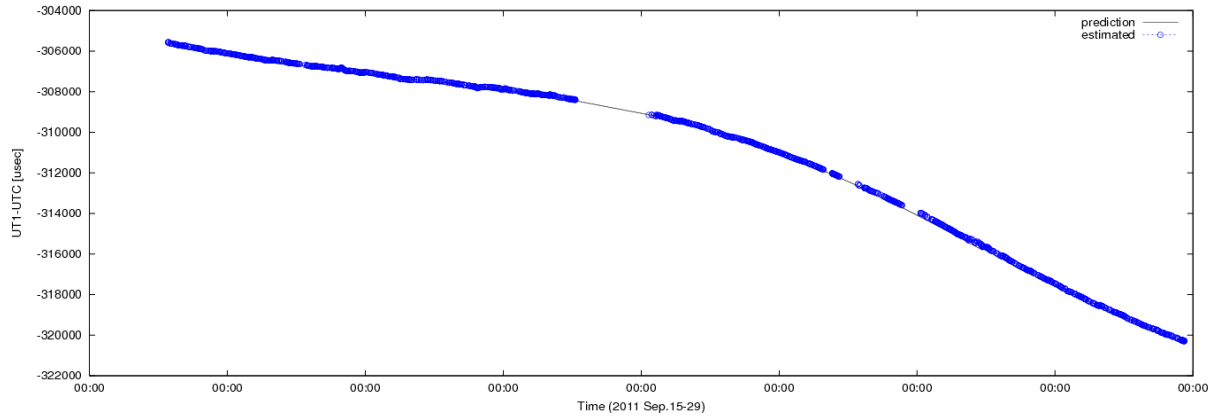


Figure 3. Continuously estimated dUT1 values using C5++ over the full 15 days of the CONT11 campaign.

4. Correlation

For logistical ease and consistency of results, and to gain experience in VLBI2010-type load, correlation was performed at a single correlator: the Washington Correlator correlated the entire CONT11 data set. The correlation parameters, such as station clock values, were kept as smooth and continuous as possible. The clocks for each station were set by examining and fitting the ‘fmout-gps’ values supplied by the stations (plotted in Figure 4 for six stations). Test correlations were done using the various phase cal tones to try to determine the tones with the least problems over all stations (see, e.g., Figure 4). The final tones (5010 for X-band and 3010 for S-band) were, at the least, no worse than any other set over all stations and 15 days. The final clock values used for correlation are listed in Table 1.

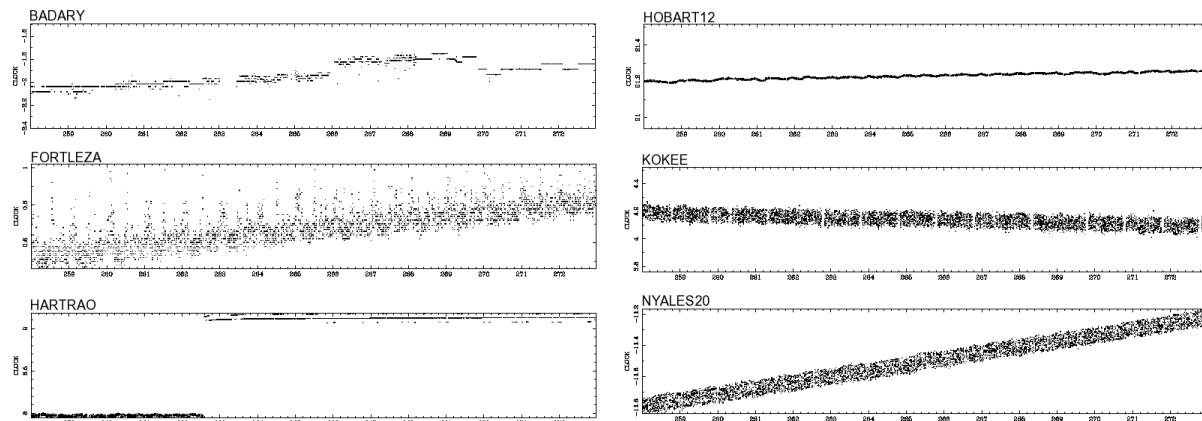


Figure 4. Clock behavior (‘fmout-gps’) during CONT11 as exemplified at six stations. The clock jump at HartRAO (Hh) is not real but rather is due to a change of the GPS reference receiver.

Table 1. Clock values used for correlating CONT11.

Station	‘fmout-gps’ [μ sec]	Used clock [μ sec]	Rate [$\times 10^{-12}$]	Comments
Bd	−2.07	−1.34	0.185	before 266–0000
		−1.20	0.160	266–0000 through 269–2109
		−1.45	0.280	after 269–2109
Ft	0.55	−7.41	0.216	
Hb	21.20	23.87	0.042	
Hh	7.97	8.54	0.006	
Kk	4.19	5.19	−0.072	
Ny	−11.99	−11.59	0.436	
On	−18.31	−26.23	0.498	
Tc	0.72	0.97	−0.0494	
Ts	0.53	1.85	−0.167	
Wf	10.75	10.86	0.008	before 264–1930
	10.75	10.78	0.008	after 264–1930
Wz	−23.34	−31.08	−0.106	
Ys	1.01	0.95	0.361	
Zc	−1.66	−1.29	0.016	

5. First Results

In the correlation process about 10% of the data were removed. The overall quality of the data after correlation is compiled in Table 2. About 97% of the correlated data has quality codes in the range 5–9.

Table 2. Overall correlation results in terms of quality codes.

Qcode	% of total scans	% of corr. scans
5–9	87%	97%
0	2%	2%
B–H	1%	1%

The average formal errors for the EOP are comparable to those of the two previous CONT campaigns. The formal errors are slightly worse in x- and y-pole and universal time, whereas the nutation parameters are better determined (Table 3). The baseline length repeatabilities (scatter) are comparable for the last three CONT campaigns for shorter baselines up to 6,000–7,000 km. For long baselines (8,000–12,000 km) CONT11 has less scatter than the CONT05 or CONT08 campaigns (Figure 5). The scatter in baseline lengths can be reduced by accounting for correlated noise between the observations at the same epoch (scan) on baselines that have a common station (Figure 6). To get a measure of the quality of the polar motion estimates we compared them with GPS estimates. The CONT11 estimates agree much more closely with GPS results (IGS final series) than polar motion from previous continuous VLBI campaigns (Table 4).

Table 3. Average EOP formal errors.

Campaign	x _p	y _p	dUT1	ψ	ε
	[μ as]	[μ as]	[μ sec]	[μ as]	[μ as]
CONT05	34	33	1.4	69	27
CONT08	36	34	1.5	59	23
CONT11	37	37	1.6	43	17

Table 4. VLBI-GPS EOP differences.

Campaign	X		Y	
	WRMS	χ^2	WRMS	χ^2
CONT05	65	2.7	40	1.1
CONT08	48	1.4	48	1.6
CONT11	33	0.8	31	0.7

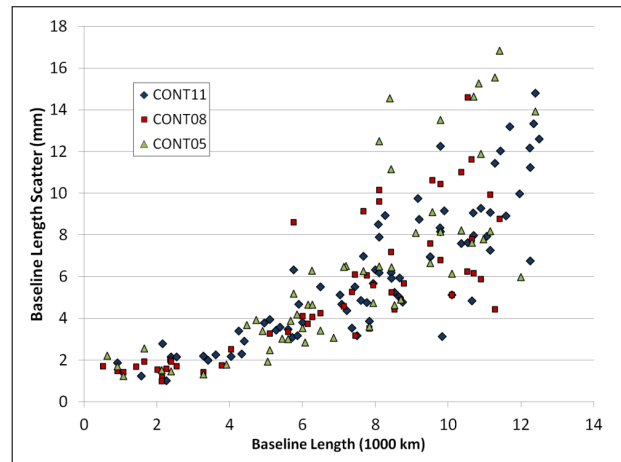


Figure 5. Baseline length scatter of the last three CONT campaigns.

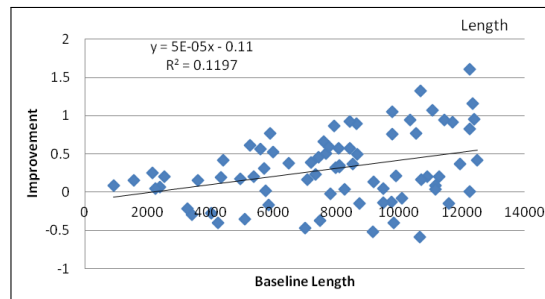


Figure 6. Reduction of baseline length scatter in CONT11 when correlated noise is taken into account.

6. Conclusions

CONT11 is one of the best continuous VLBI campaigns observed yet. It can be considered as a precursor to VLBI2010 continuous observing. Specifically, the staggered individual station check times effectively prevented observational gaps which had caused discontinuities in the high-frequency EOP series in earlier campaigns, and session days were from 0 UT to 24 UT conforming with observing by other geodetic techniques. In terms of analysis results, baseline length repeatabilities and polar motion estimates were better than in previous CONT campaigns. The high quality of this continuous set of data will certainly be valuable for geophysical investigations.