

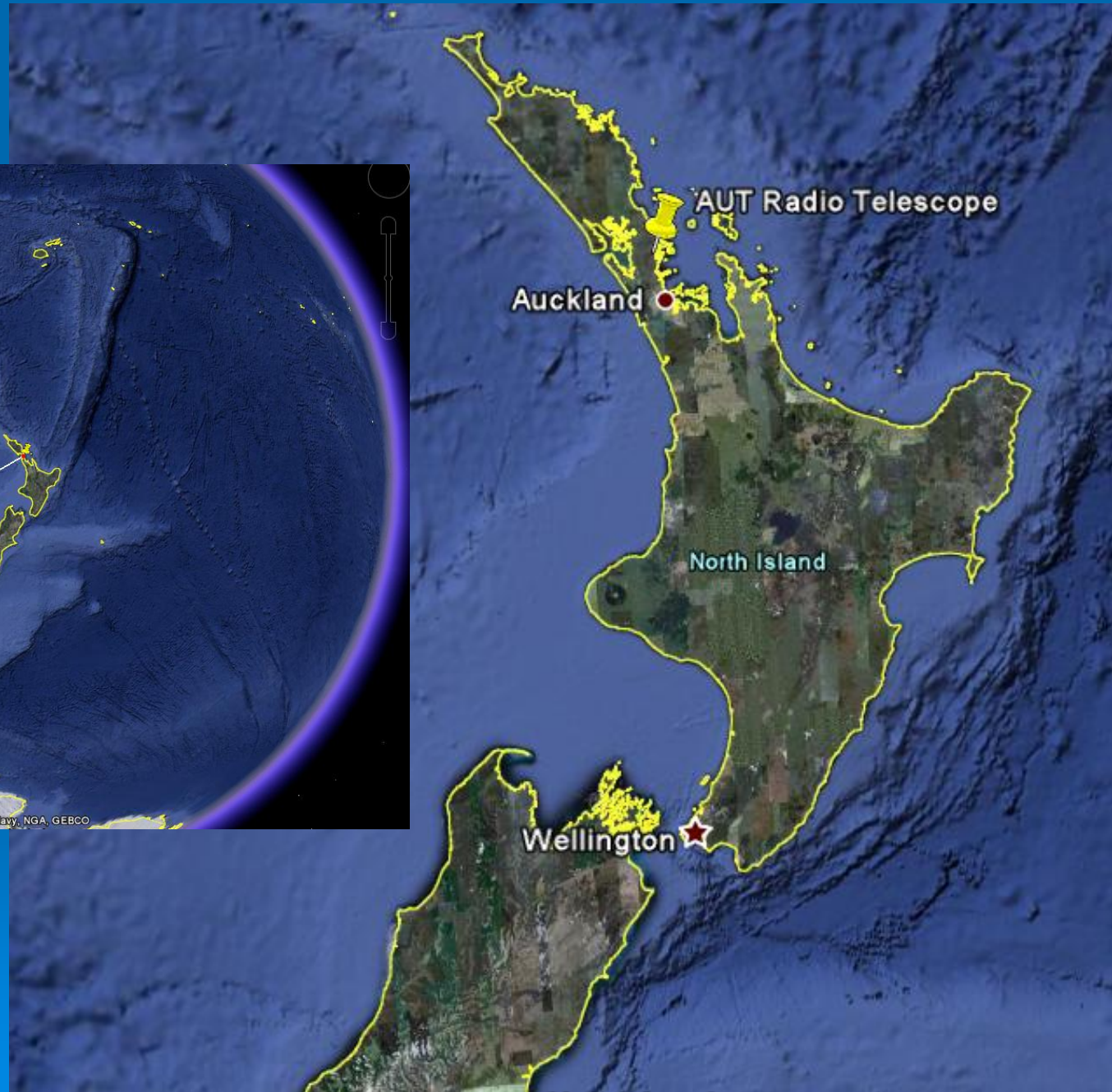


The AUT 12 metre Telescope Characterisation and Calibration



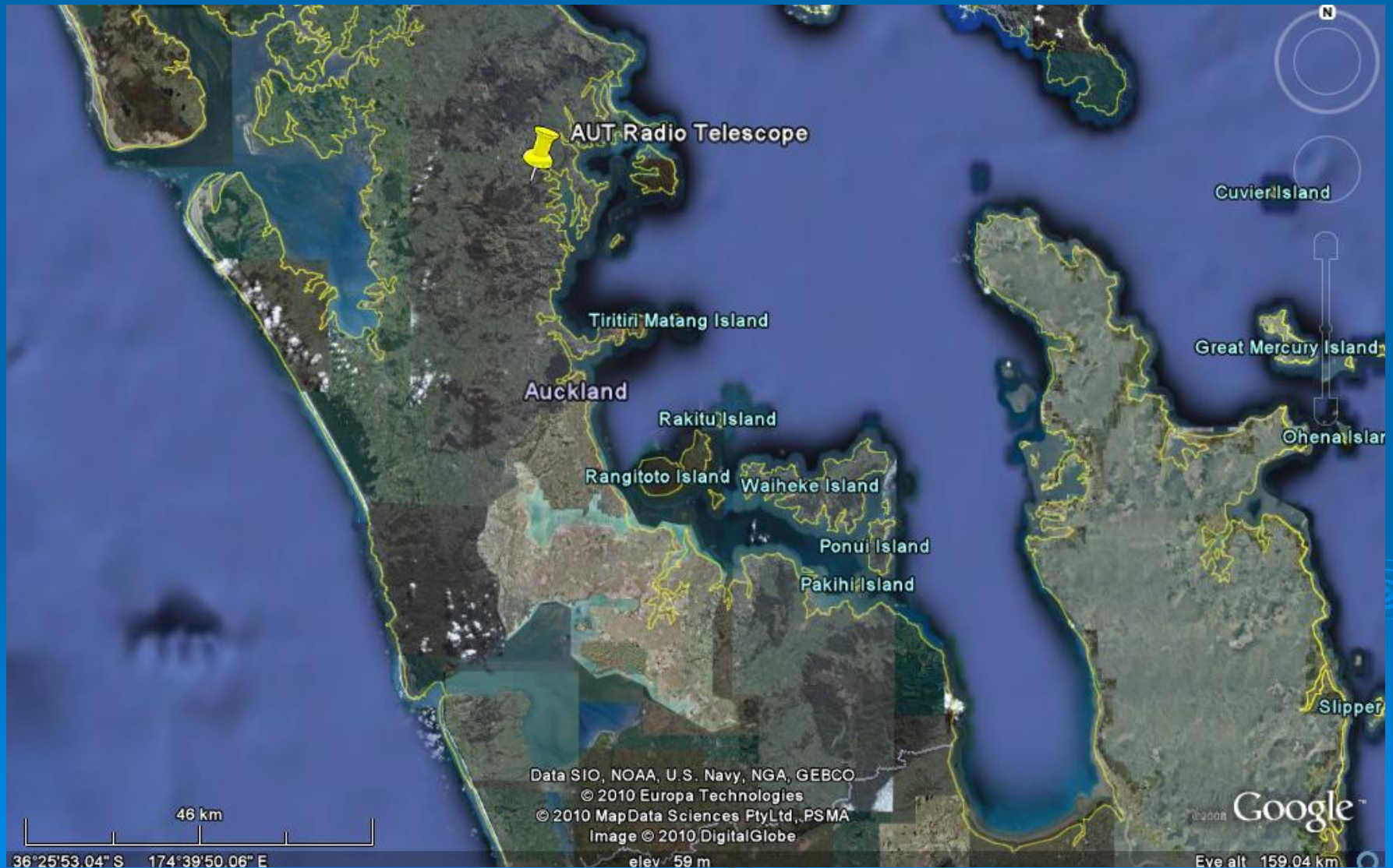
Tim Natusch
Sergei Gulyaev





Warkworth

60 km North of Auckland



Baselines to Australia



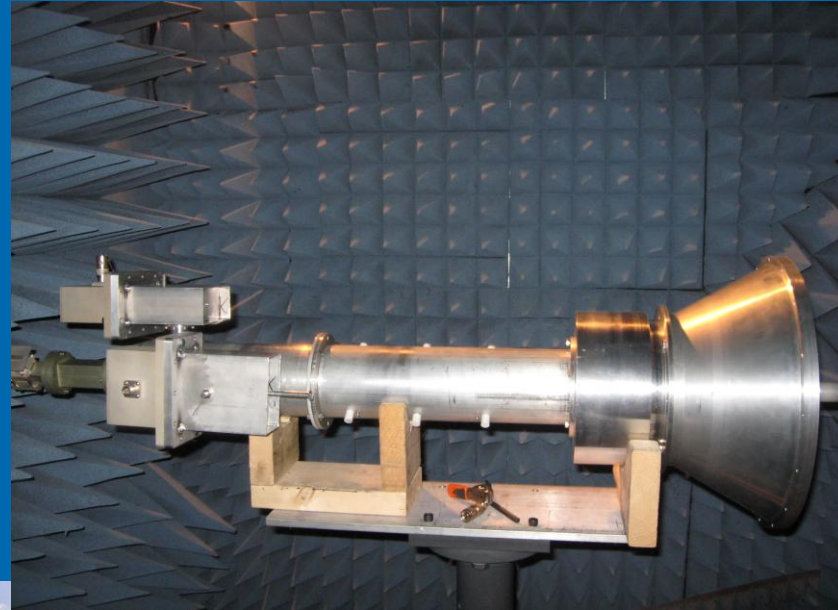
Antenna

- Cobham / Patriot
- 12m Cassegrain
- Maximum Slew rates:
 - Azimuth = 5 deg s^{-1}
 - Elevation = 1 deg s^{-1}
- Currently equipped with dual polarisation dual frequency S/X feed



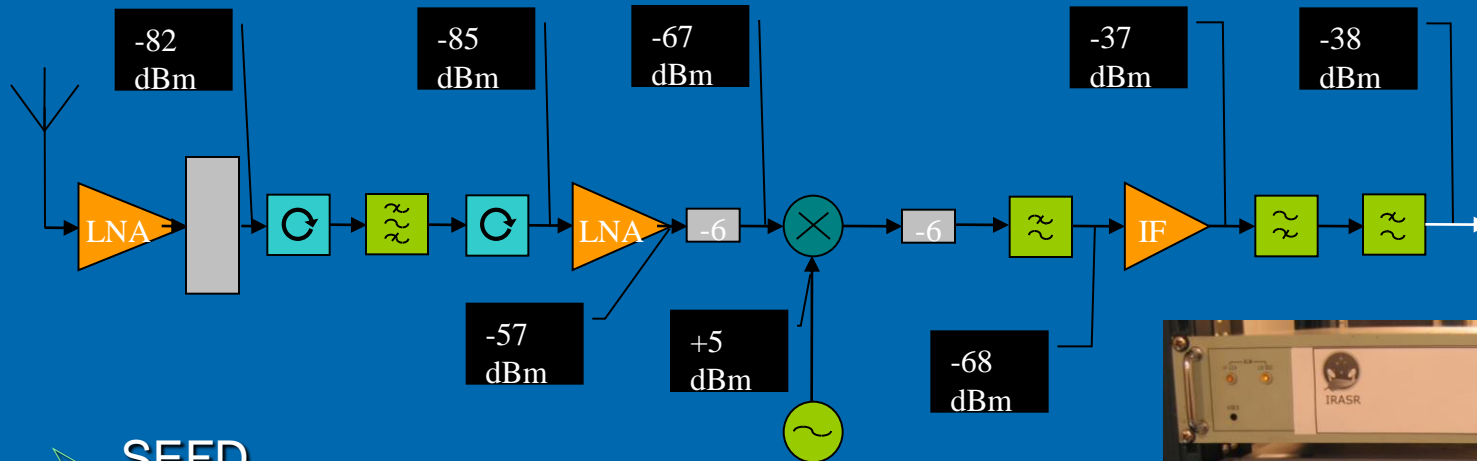
Feed

- Coaxial S/X
 - S band 2.1 to 2.4 GHz
 - X band 8.1 to 9.1 GHz
 - RCP & LCP both bands
- $\frac{1}{4}$ wave plate polariser S Band
- Septum OMT polariser X Band



Receivers

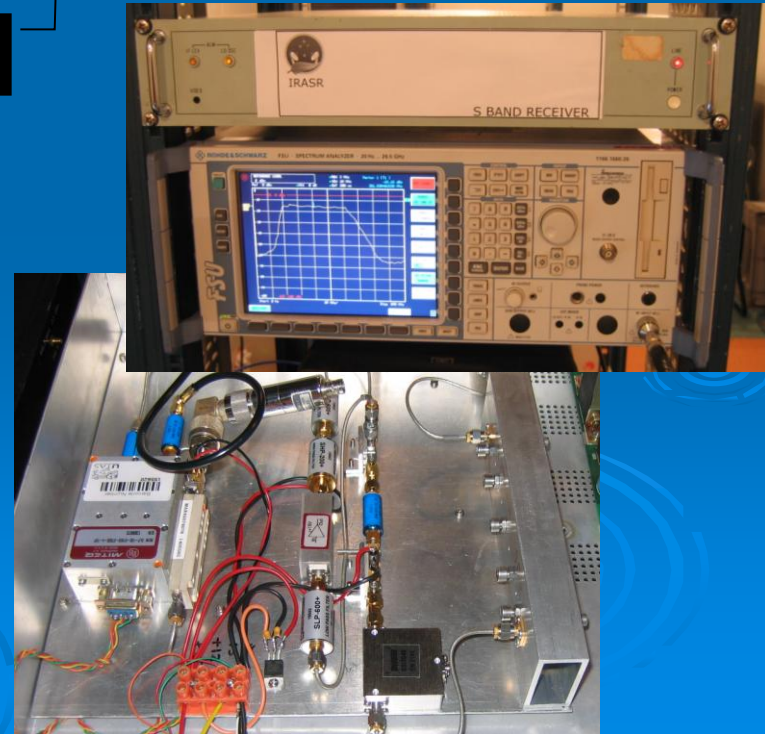
- Room temperature un-cooled design
- Superheterodyne receiver (powers in 1 MHz bandwidth)



➤ SEFD

- ≈ 4000 Jy @ S Band
- ≈ 5000 Jy @ X Band
- Improvements expected; feed redesign

- Thanks to Peter McCulloch and UTAS for generous assistance with receiver development!



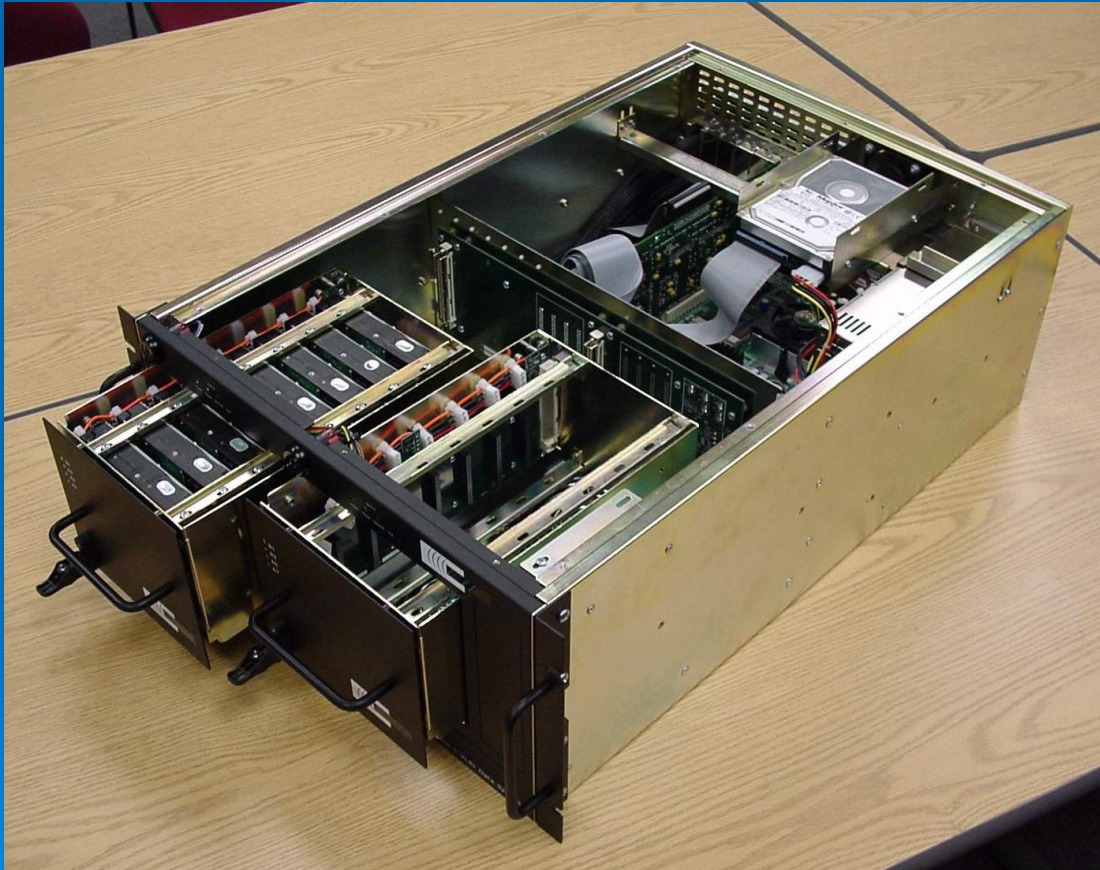
Frequency Standard

- Hydrogen Maser
Symmetricom MMH2010
 - 5, 10, 100 MHz outputs
 - Allan deviation
 - 1s $2.0E-13$
 - 1000s $3.2E-15$
 - Floor $3.0E-15$
 - Long term drift : $<2.0E-16$ per day
- Temperature stabilised room: currently system holds temperature to within 2 deg C swing, working on getting this down to <1 deg.



Data Recorder

- Haystack MIT Mk 5 B+

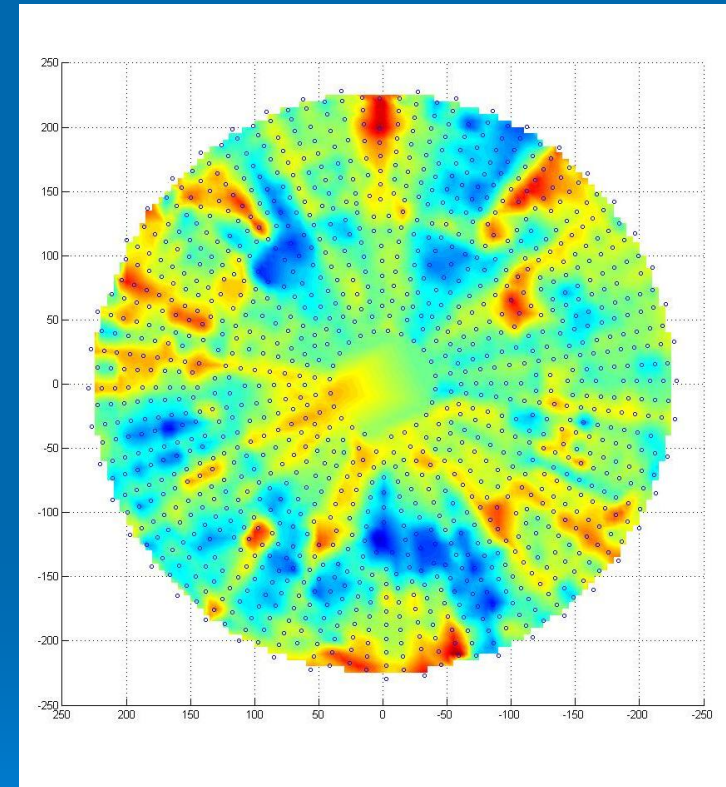


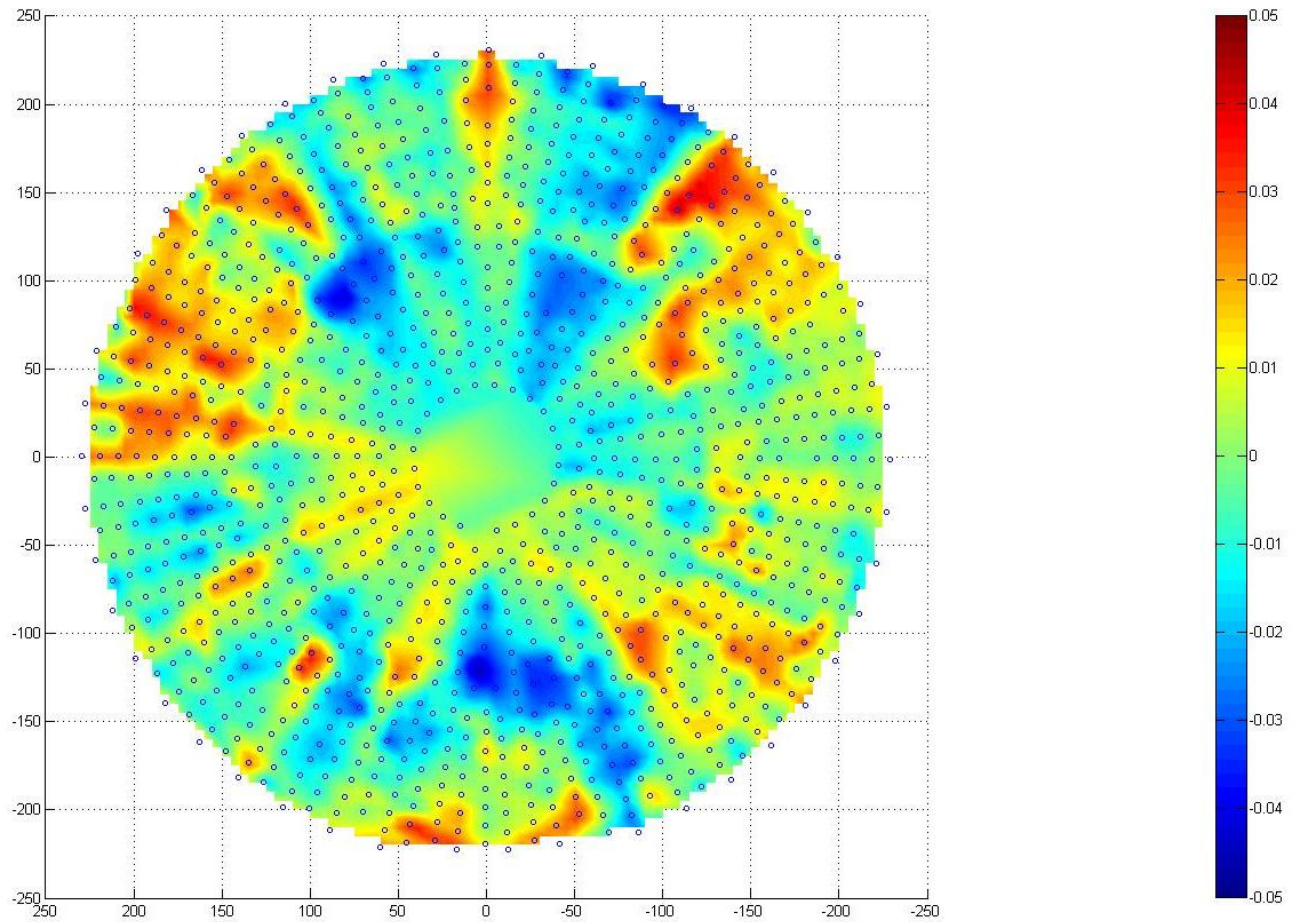
Digitiser

- DBBC (HAT Lab INAF/IRA)
- Ordered, delivery expected March 2010
- Geodetic configuration
 - 4 channel recording
 - 2 x 1 GHz @ X band
 - 2 x 500 MHz @ S band

Primary surface alignment

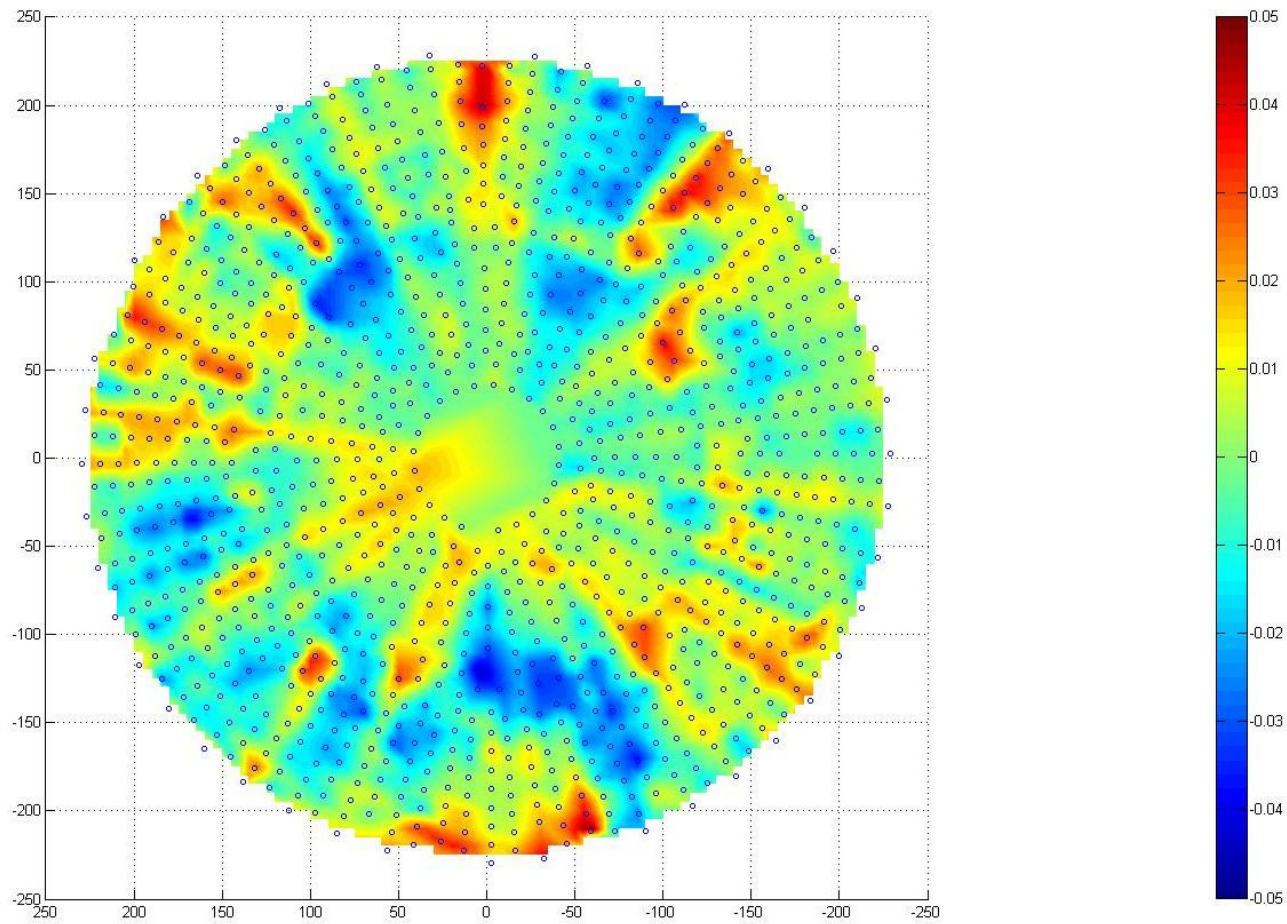
- Surface alignment conducted by extensive Photogrammetric testing; rms ≈ 0.35 mm
- Plan RF holography on surface in future to confirm the Photogrammetry results and further refine if possible





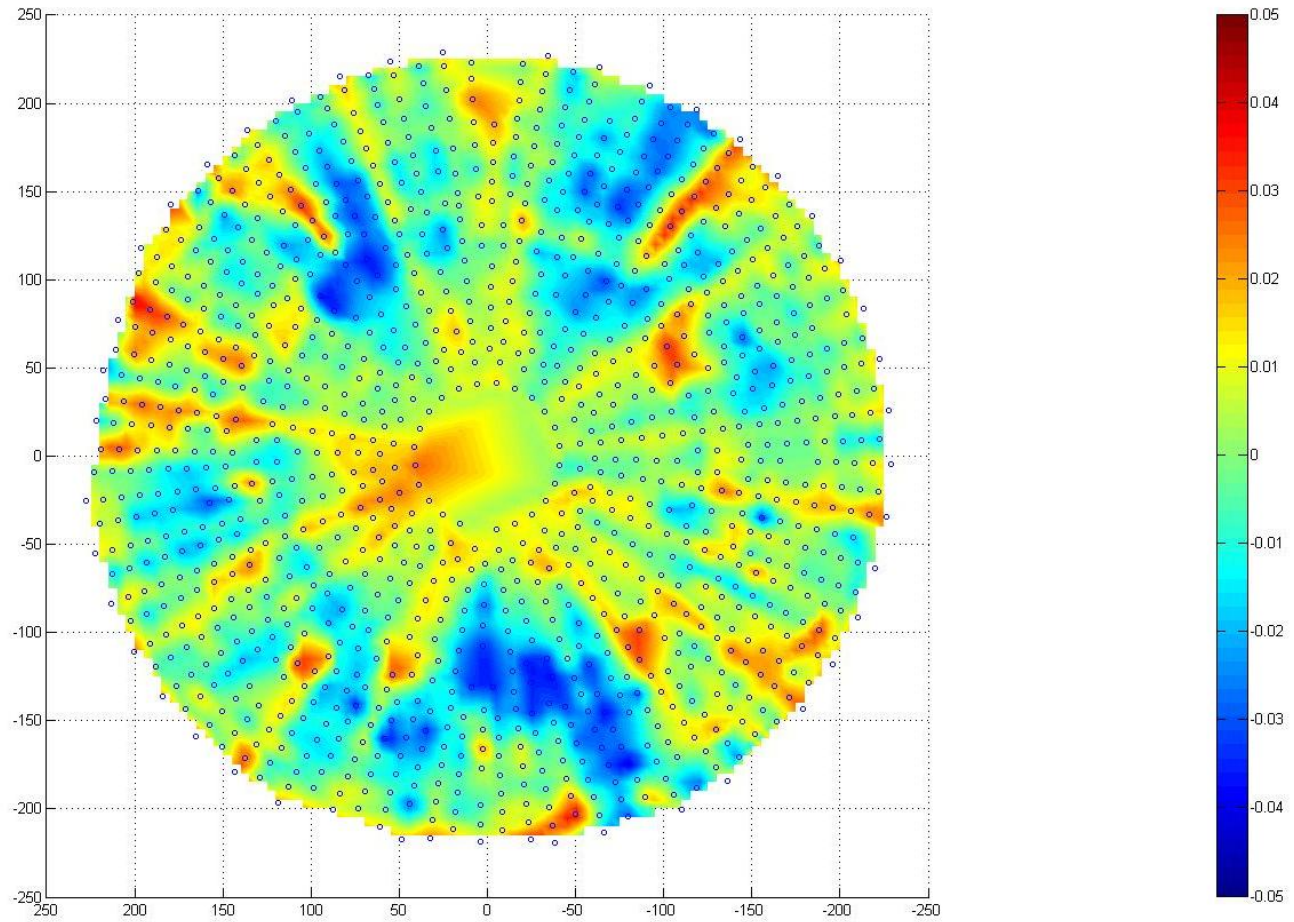
El = 10 deg

rms = 0.0148''



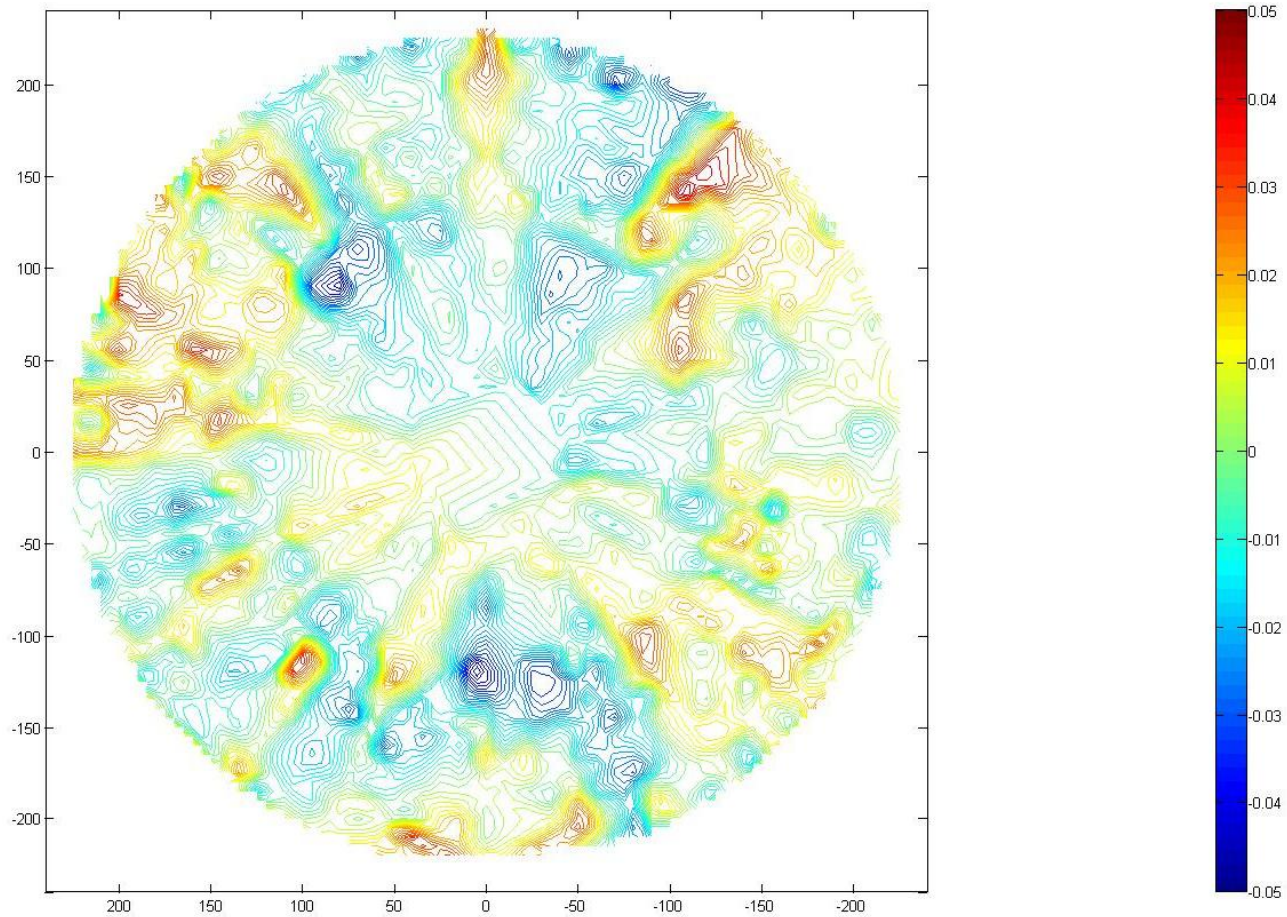
El = 50 deg

rms = 0.0142"



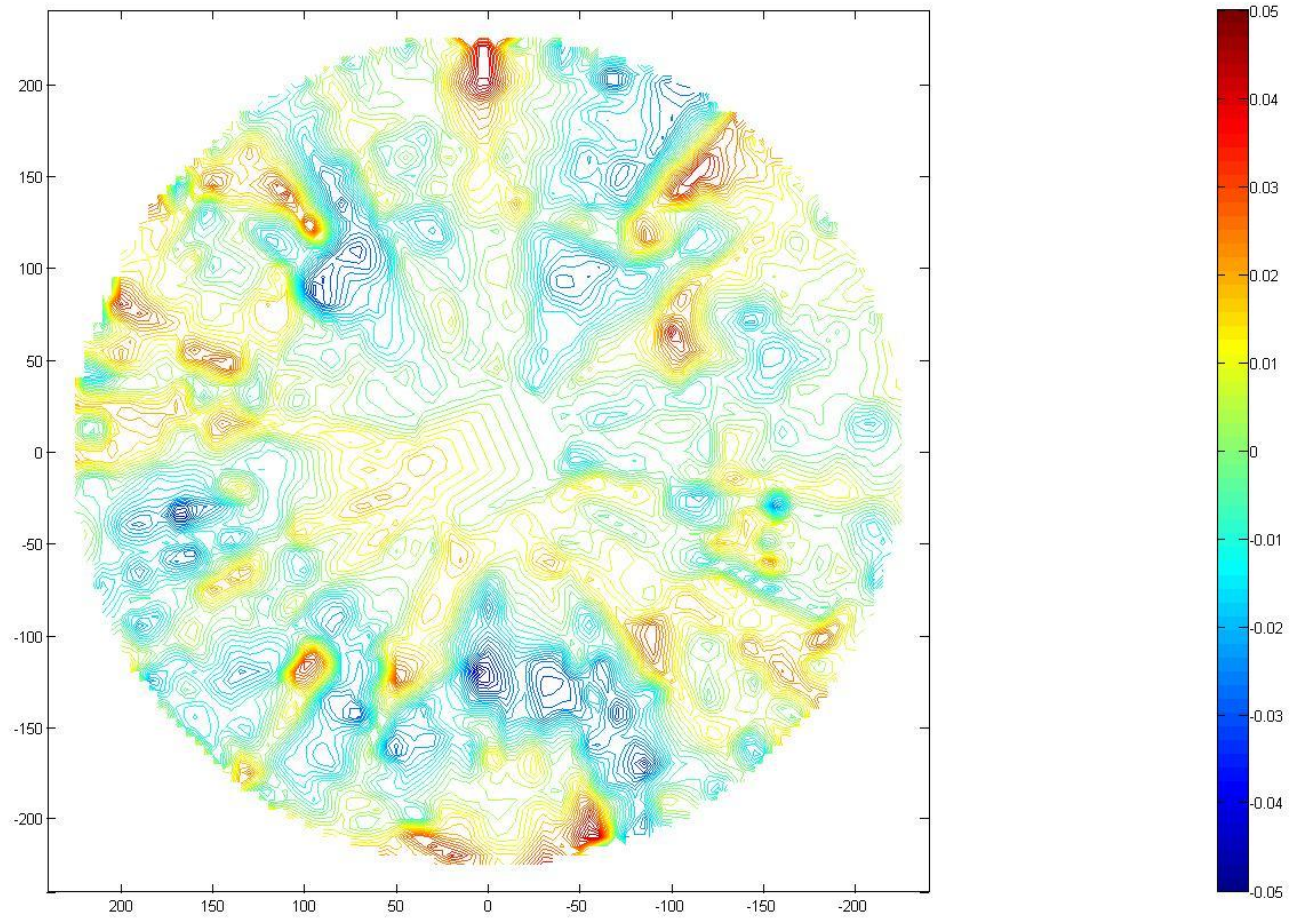
El = 88 deg

rms = 0.0145"



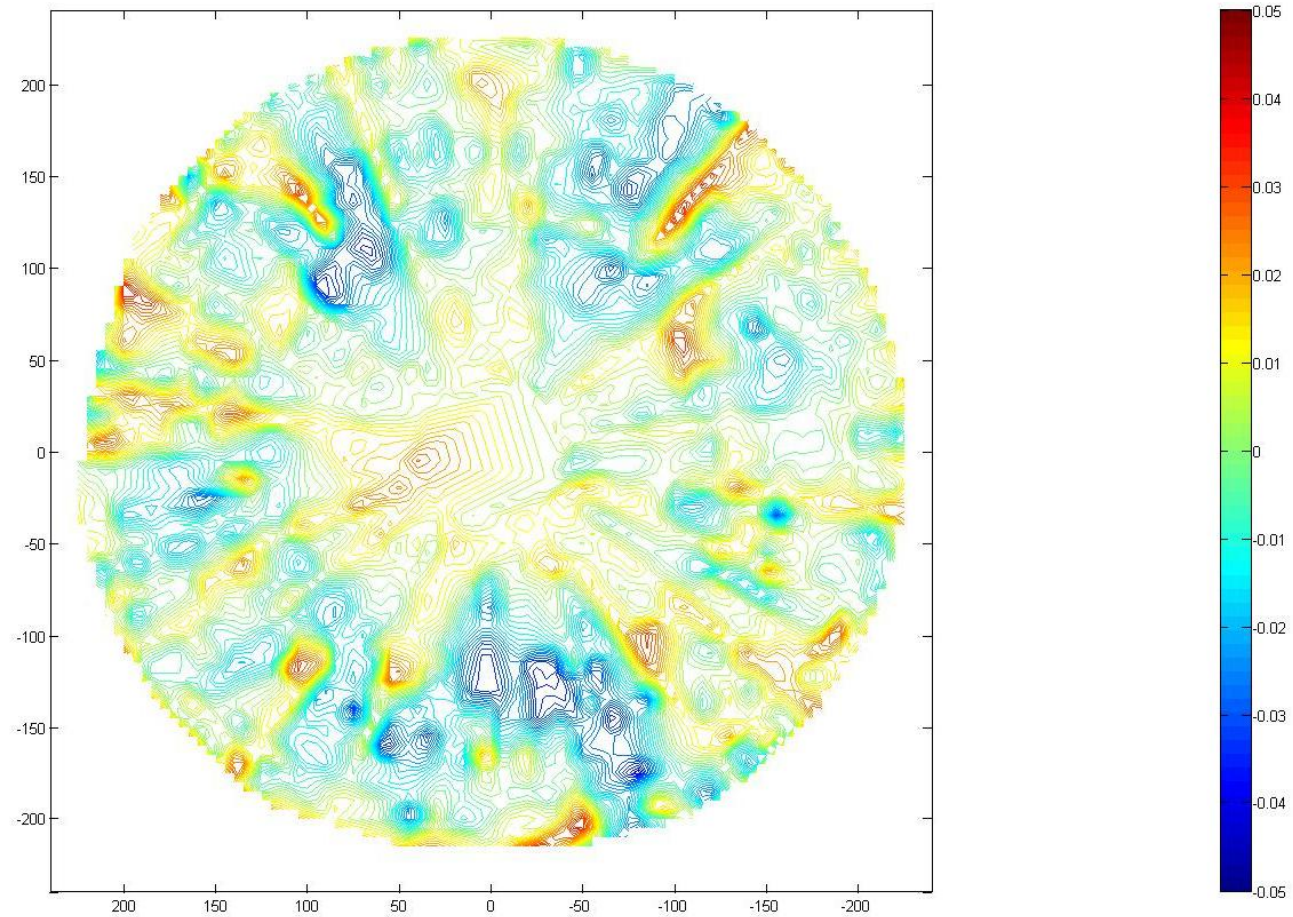
El = 10 deg

rms = 0.0148"



El = 50 deg

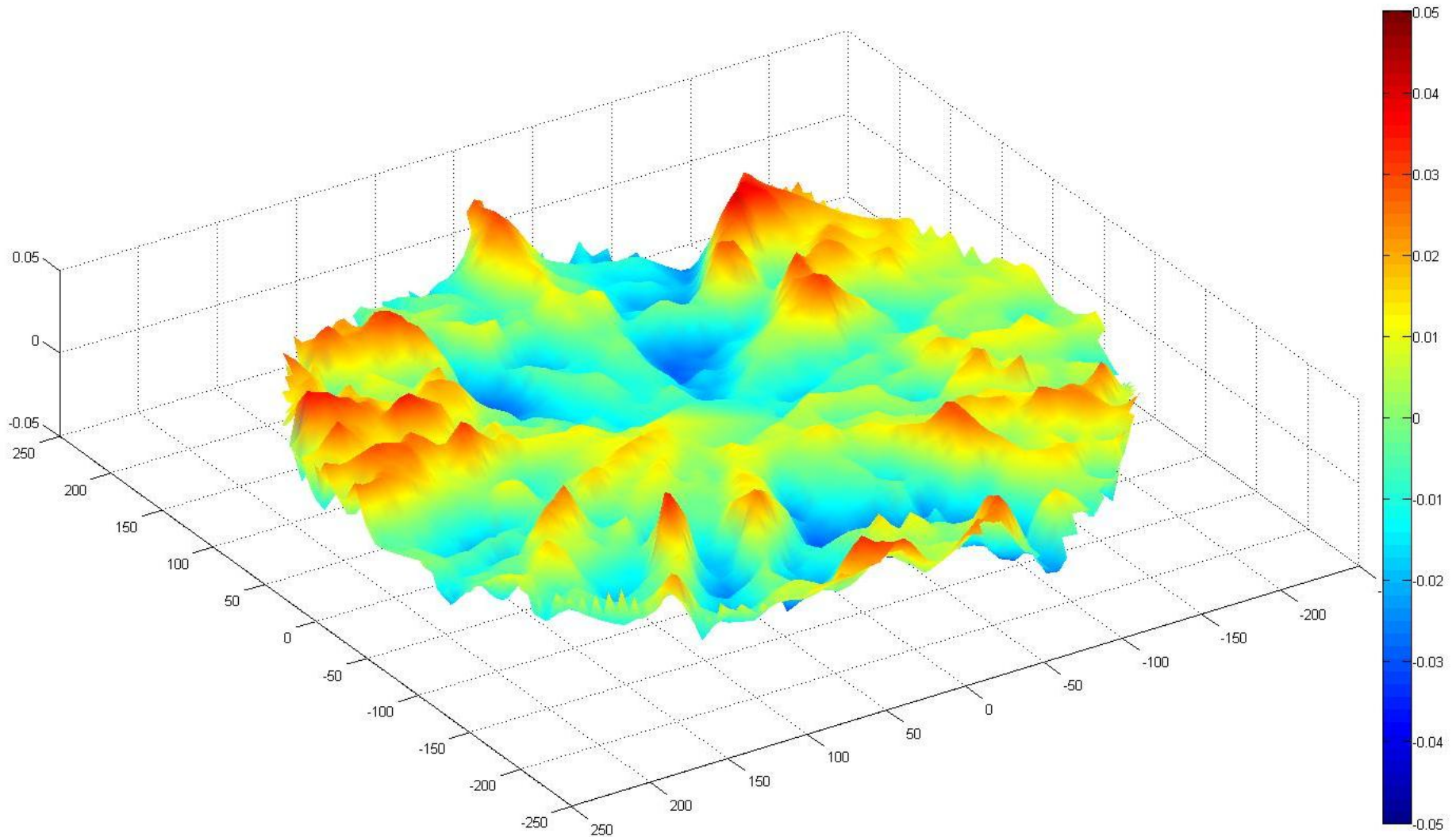
rms = 0.0142"



El = 88 deg

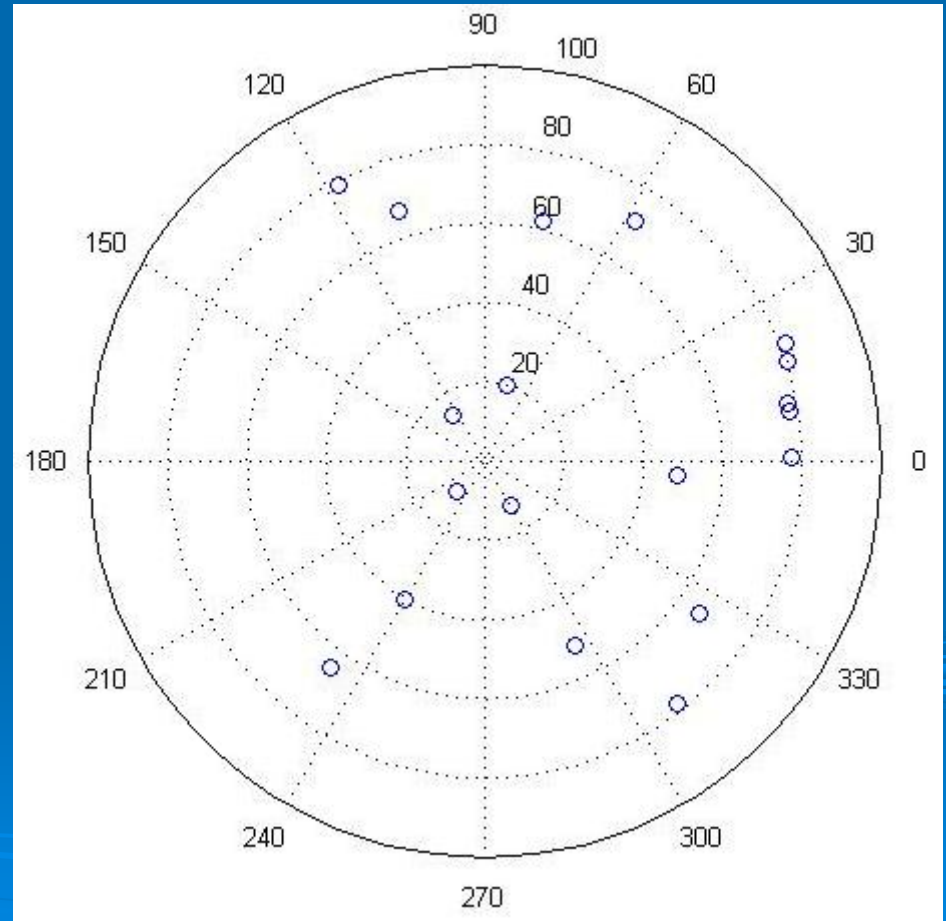
rms = 0.0145"

10 Deg Elevation, surface deviations in mm



Pointing models and calibration

- Work in progress
- S band observations



Nine term pointing model built into control system

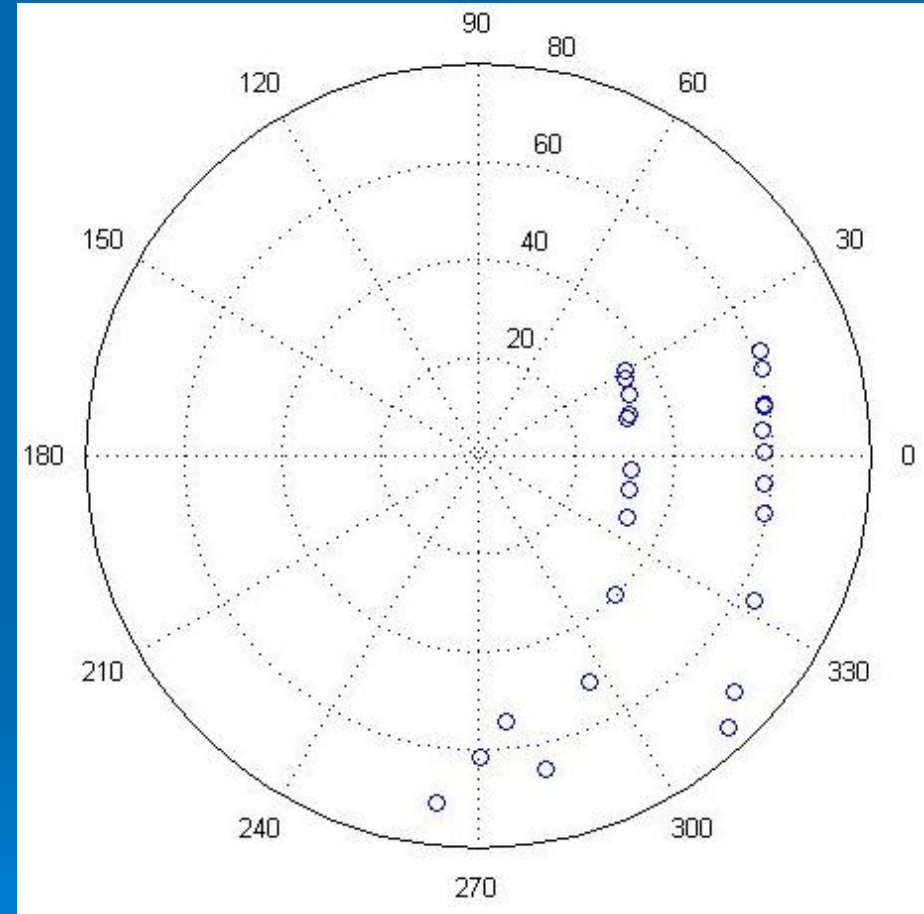
$$dXE1 = p1 + p2*\cos(E) + p3*\sin(E) + p4*\sin(E).*\cos(A) + p5*\sin(E).*\sin(A)$$

$$dE1 = -p4*\sin(A) + p5*\cos(A) + p7 + p8*\cos(E) + p9*\cot(E)$$

- Least squares fit of model and X band data to 25 measurements

p1	0.1218	
p2	-0.4861	Az encoder offset
p3	-0.0576	
p4	0.1266	
p5	-0.0254	
p7	0.5119	Elevation encoder offset
p8	0.0586	
p9	-	
0.0173		
dAfit_error =		
0.0328		
dEfit_error =	0.0344	

- Have not combined S + X band measurements due to S band beam squint

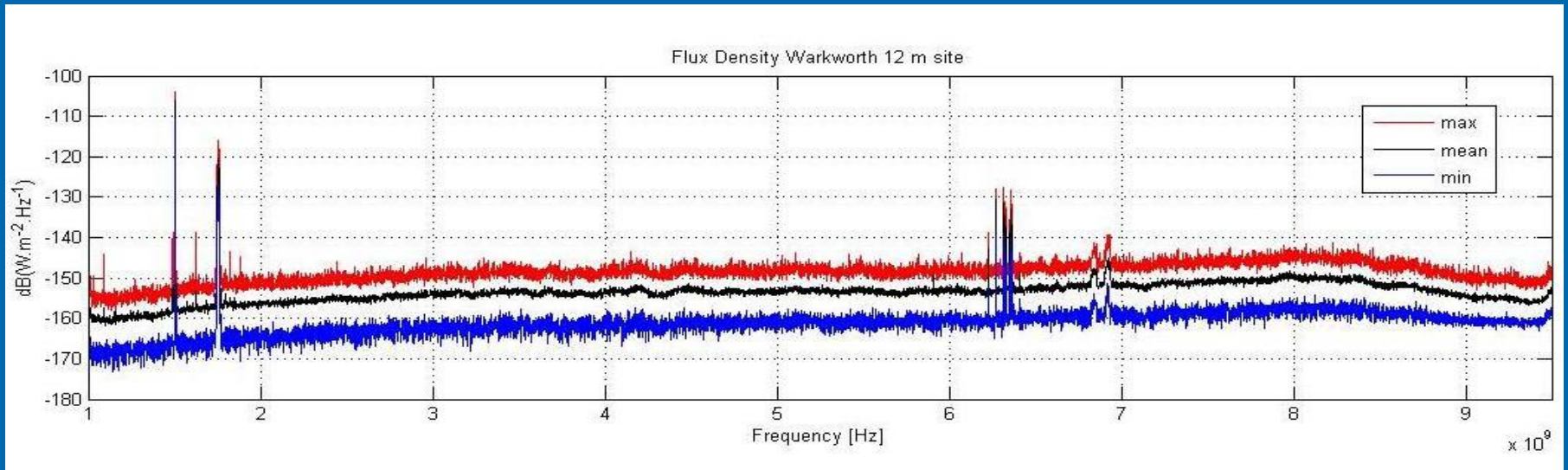


S Band squint

- Detected offset of S band beams relative to X band
- Elevation offsets dominate
- S band RCP ≈ -0.15 deg.
LCP $\approx +0.07$ deg.
- No detectable offset X_{RCP} to X_{LCP}

RFI situation

- Initial RFI measurements (thank you to staff of ATNF for assistance)



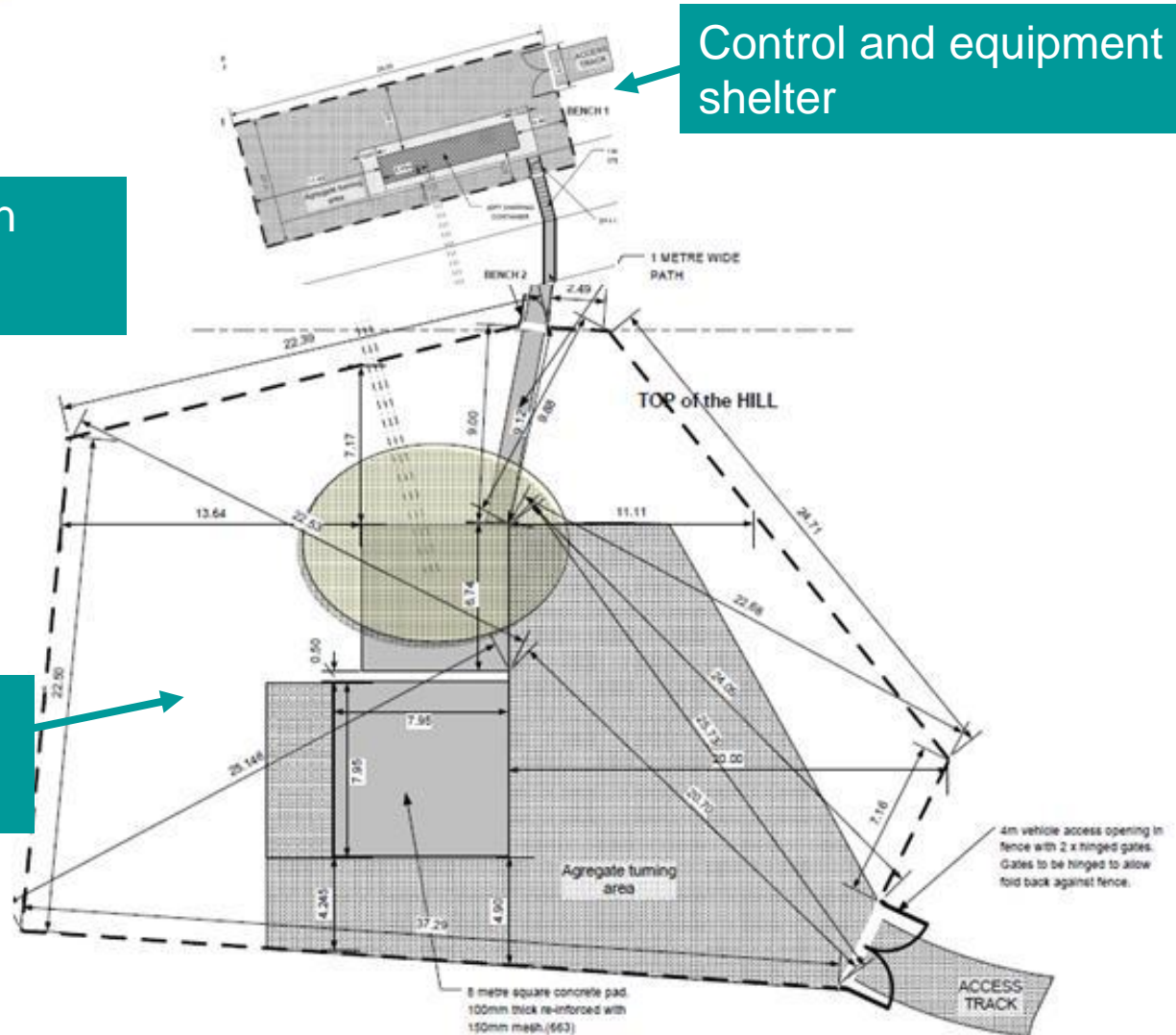
- 1 problem identified in S band subsequent to antenna construction
 - 2.11 GHz; Vodafone NZ inter cell site data link #@\$!!!
 - Notch filter to suppress
- X Band clean

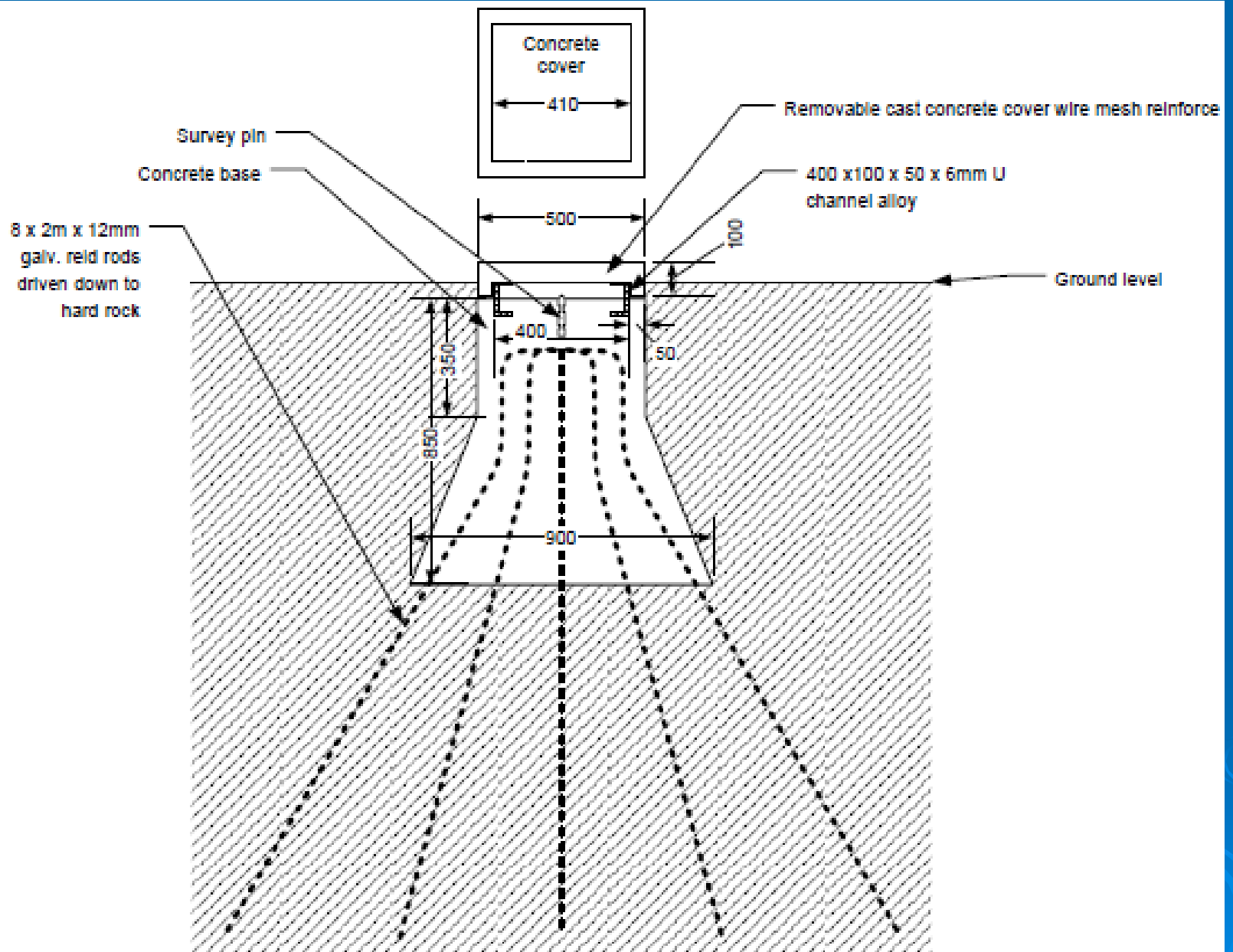
Site plans and detail

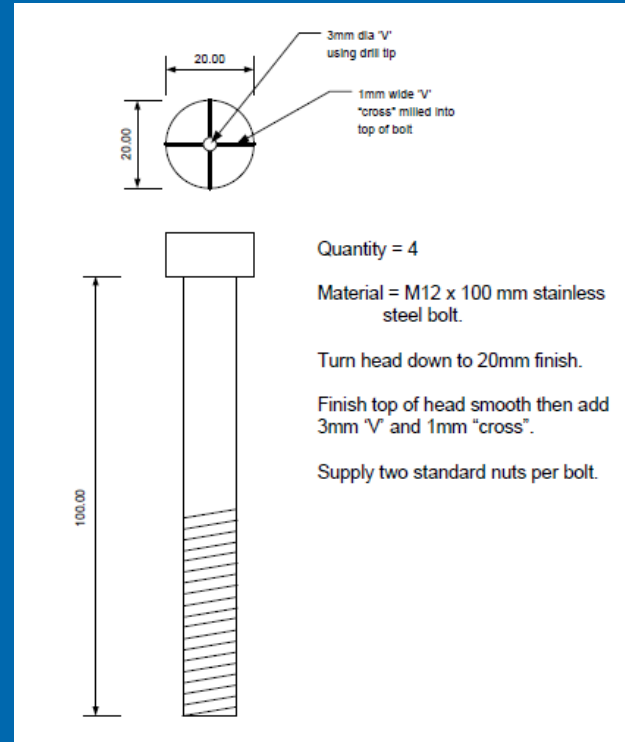
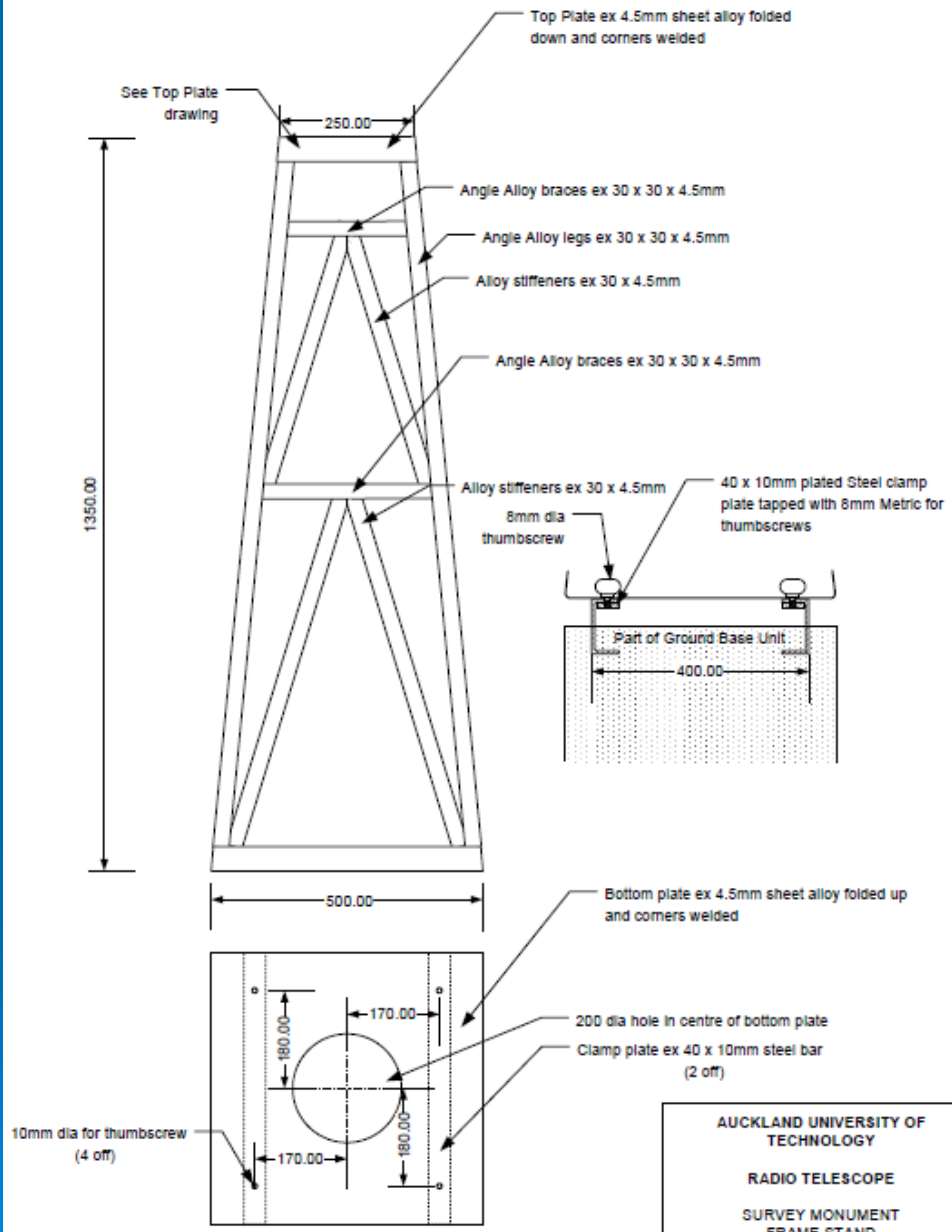


Co sited GPS station
GNS / LINZ

Antenna compound







Network connectivity

- Expect 1 Gbps connectivity to KAREN
March 2010
- KAREN = Kiwi Academic Research
Network
 - 10 Gbps backbone
 - 155 Mbps connection to Australia
 - 625 Mbps connection to Seattle

Control System interface

- Manufacturer supplied simple HMI program

POWER/STATUS | **COORD SYS** | **AZ/EL** | **LOAD TRACK** | **SETTINGS** | **DIAGNOSTICS** | **COMMS**

AZ/EL RUN MODE

STOP | **STOW**

POSITION SETPOINTS (deg)
POSITION: AZ EL

VELOCITY SETPOINTS (deg/sec)
VELOCITY: AZ EL

TRACK

Tracking in EQUATORIAL COORDINATES

EQUATORIAL MODE TRACKING

DATA SOURCE
ARRAY | **SETPOINT**

RA/DEC SETPOINTS
RA DEC

RA/DEC OFFSETS
STOP

RA/DEC OFFSETS
POSITION: RA DEC

AZ START TURN
-1 | 0 | +1 | **AUTO** | **OK**

AZ/EL OFFSET MODE

STOP

POSITION OFFSETS (deg)
POSITION: X-EL EL

VELOCITY OFFSETS (deg/sec)
VELOCITY: AZ EL

CURRENT POSITION

AZIMUTH | **ELEVATION**

POS ERROR: |

CURRENT VIRTUAL AXES VALUES

AZIMUTH | **ELEVATION**

RA | DEC

CURRENT TIME

MJD | **Seconds**

CLOCK INITIALIZED | **SNTP SERVER OK**

SOFT LIMITS

Azimuth	Elevation
LOW	LOW
HIGH	HIGH

DEMAND LIMITING

Azimuth	Elevation
LOW	LOW
HIGH	HIGH
SPEED	SPEED

HARD LIMITS

Azimuth	Elevation
LOW	LOW
HIGH	HIGH

DISPLAY UPDATE

INTERVAL ms **ENABLE** | **LOAD**

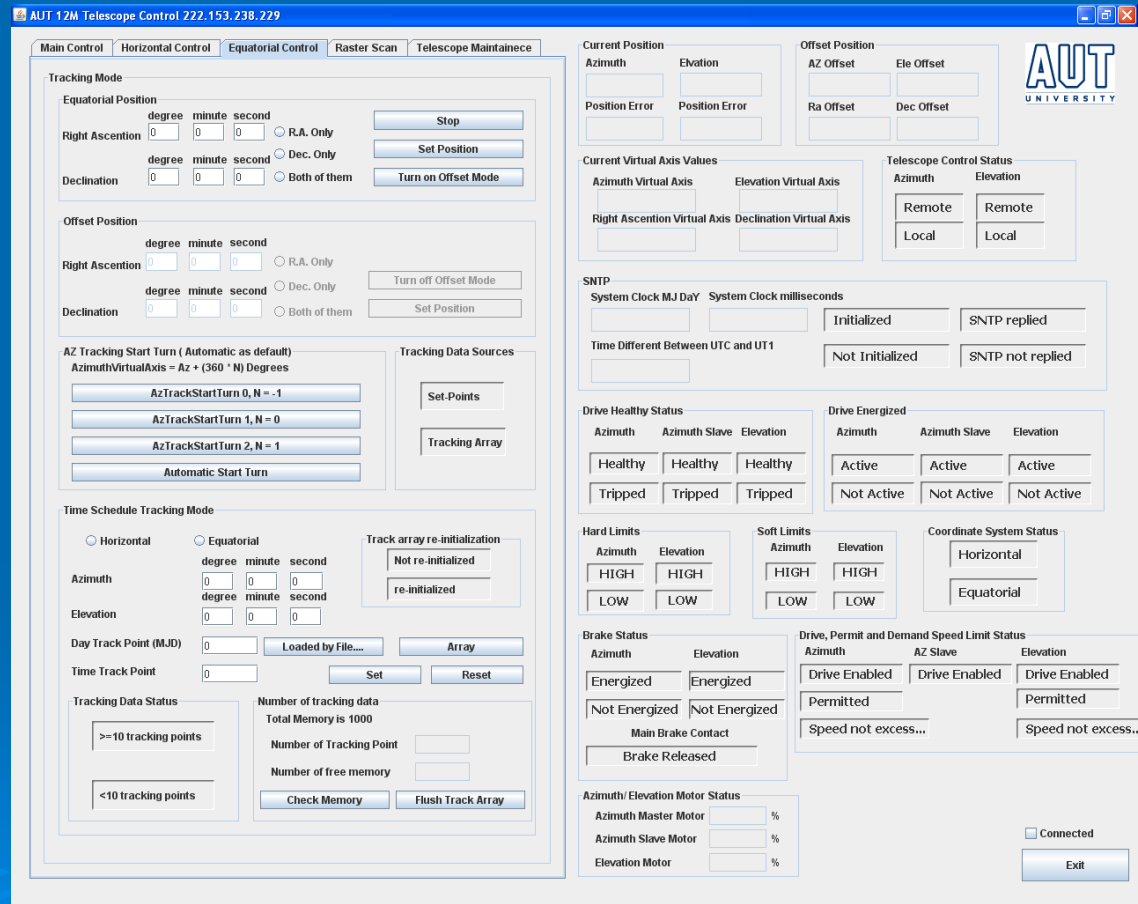
MOTOR CURRENTS (% of Rated)

AZIMUTH		ELEVATION
MASTER	SLAVE	
<input type="text" value="000"/>	<input type="text" value="000"/>	<input type="text" value="000"/>

EXIT

Development of AUT Software interface

- Java + Modbus-TCP
- All basic control functions implemented
- Adding features to interact with data recording, system calibration and logging systems
- Probably won't use this, want to use AUSCOPE interface for compatability



Acknowledgements

- UTAS for assistance with Receiver design
- ATNF for help with RFI investigations
- Steven Tingay for supporting development of VLBI capability in NZ