



# **VLBI-SLR Combination Solution Using GEODYN**

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# Overview



- Background and Motivation
- Geodyn Solution Procedure
- Comparison of GEODYN and CALC/SOLVE Solutions
- VLBI + SLR Combination Solution
- Conclusions



# Background and Motivation



- IERS currently makes an ITRF from technique solutions from each technique analysis center (VLBI, SLR, GPS, DORIS)
- Problems with this method of combination:
  - Inconsistent a priori models
  - Different analysis software used by technique analysis centers
  - Different solution parametrizations used in technique analysis center solutions



# Background and Motivation



- Working Group on Combination at the Observation Level was started by IERS
- To improve precision, resolution, and consistency of EOP, TRF, and CRF products
- Questions to be resolved:
  - weighting of different techniques
  - accuracy of colocation site ties
  - effect of common technique parameters like troposphere and clocks



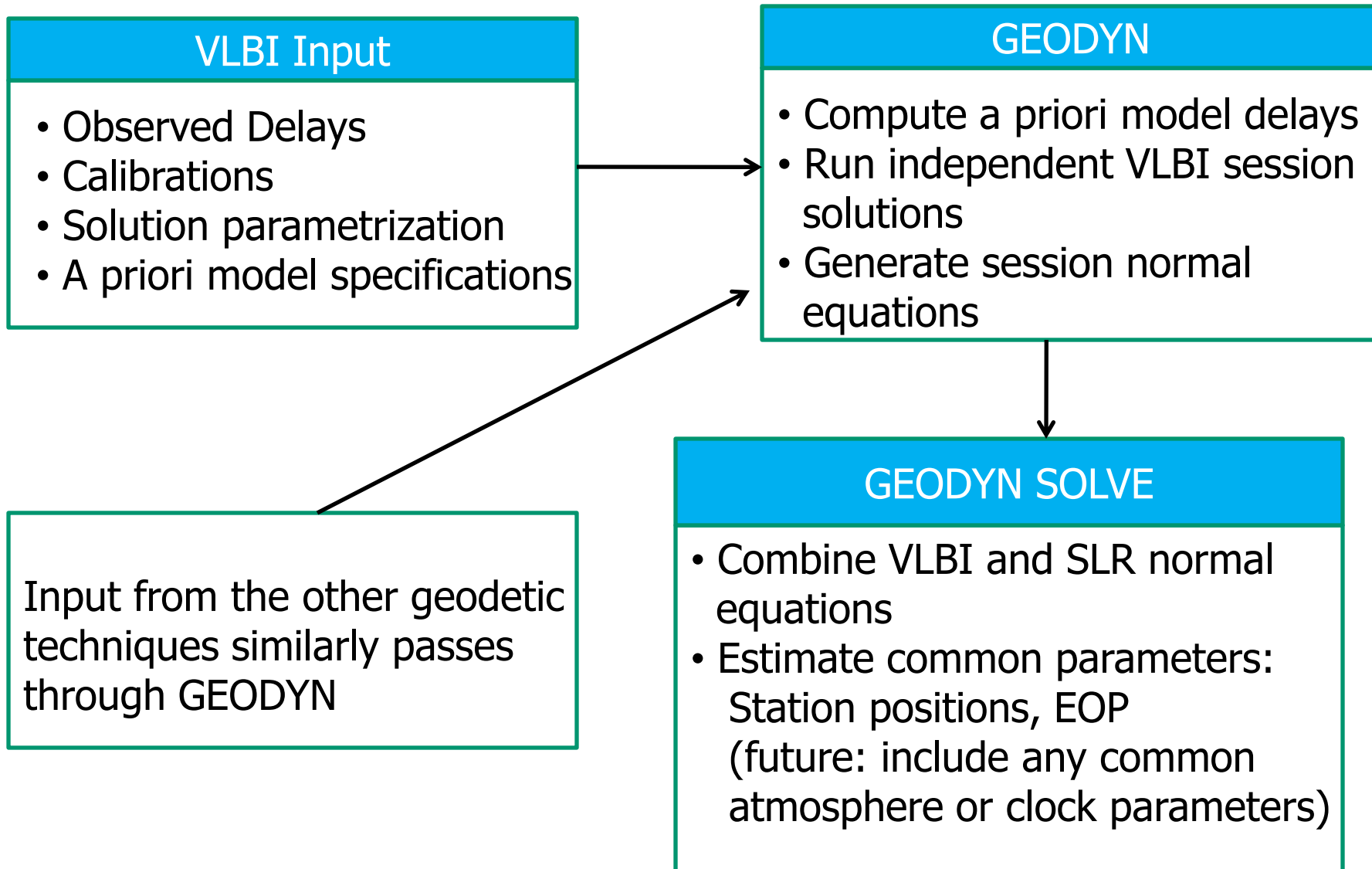
# Background and Motivation



- We want to generate a multi-technique solution using
  - 1) same analysis software
  - 2) same a priori models
- Our goal is to combine all the geodetic techniques at the observation level
- We use GEODYN to initially make a VLBI + SLR combination solution



# GEODYN Solution Procedure





- Compared solutions for single 24-hour VLBI solutions using CALC/SOLVE and GEODYN.
- *A priori* position coordinates are in ITRF2005. *A priori* EOP series was IERS C04.
- Standard VLBI solution parametrization:
  - 20 minute troposphere parameters
  - 60 minute clocks
  - daily EOP estimated at session midpoint
  - station coordinates
- Each day was processed independently.
- We ran two types of solutions for sessions observed from 2007-2008
  - 1) estimate EOP and fix site positions to ITRF2005.
  - 2) estimate both EOP and site positions



# CALC/SOLVE vs. GEODYN



Solution 1. Estimate EOP and fix site positions (2007-2008)

Difference Statistics

Parameter	Bias	WRMS	Chi2
X-Pole (uas)	9.6	46	1.31
Y-Pole (uas)	-1.2	37	0.97
UT1 (us)	-0.47	1.9	1.09

Solution 2. Estimate both EOP and site positions (2007-2008)

Difference Statistics

Parameter	Bias	WRMS	Chi2
X-Pole (uas)	16.5	64	1.09
Y-Pole (uas)	-14.2	71	1.29
UT1 (us)	-0.41	3.4	1.57

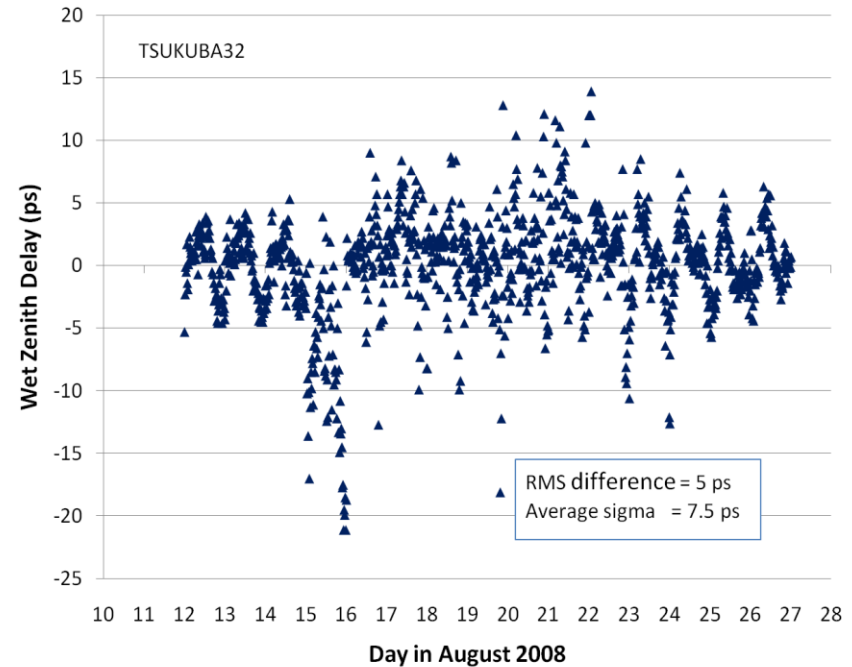
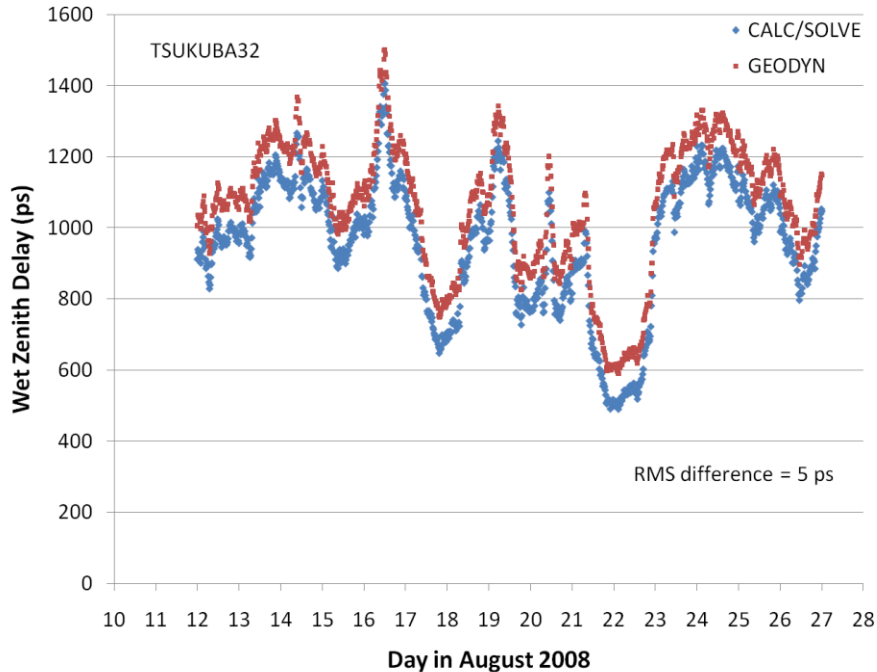




# CALC/SOLVE GEODYN Comparison



## CONT08 Wet Zenith Delays



Comparison of the wet zenith delays estimated every 20 minutes at TSUKUB32 using CALC/SOLVE and GEODYN. The series were offset by 100 ps for clarity.

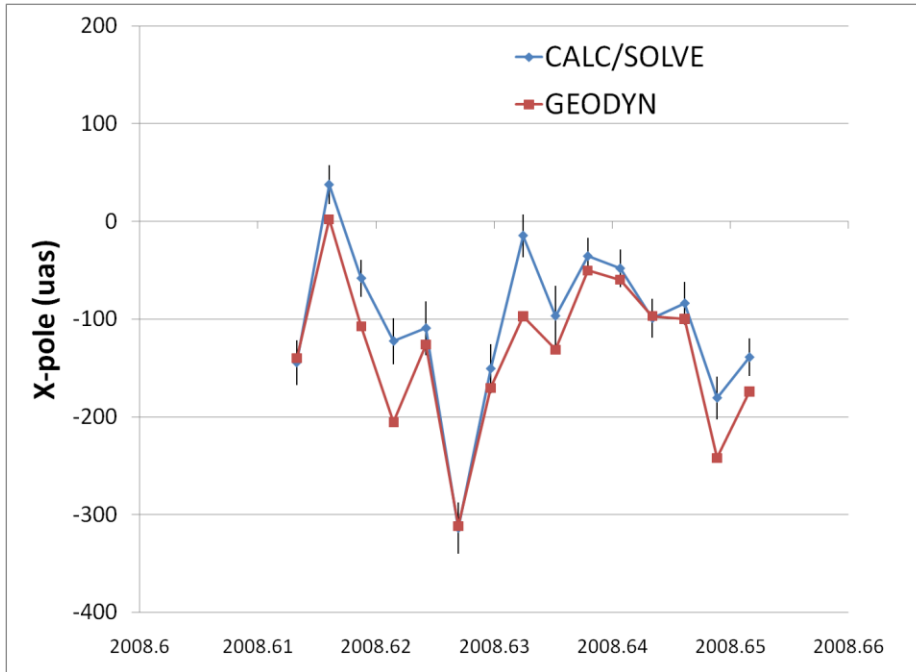
Daily signal in difference => Modeling difference



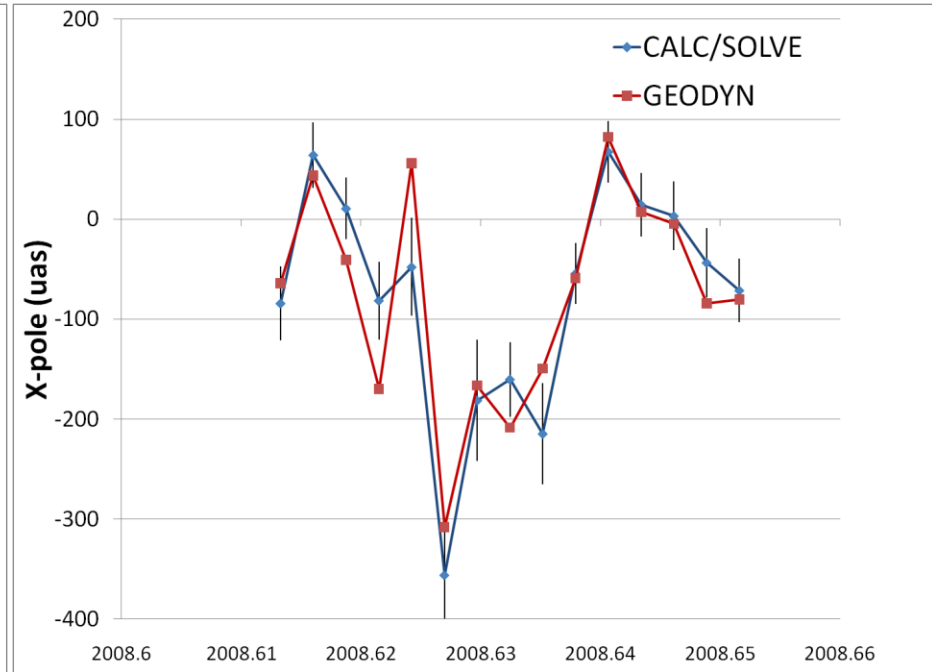
# Calc/Solve GEODYN Comparison



CONT08



Station positions were fixed



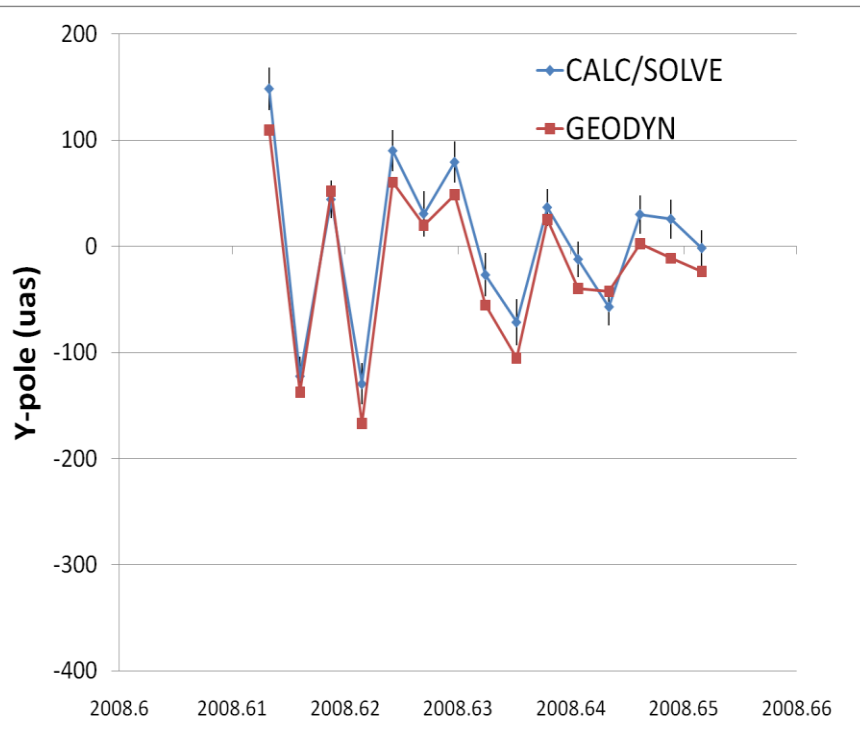
Station positions were also estimated



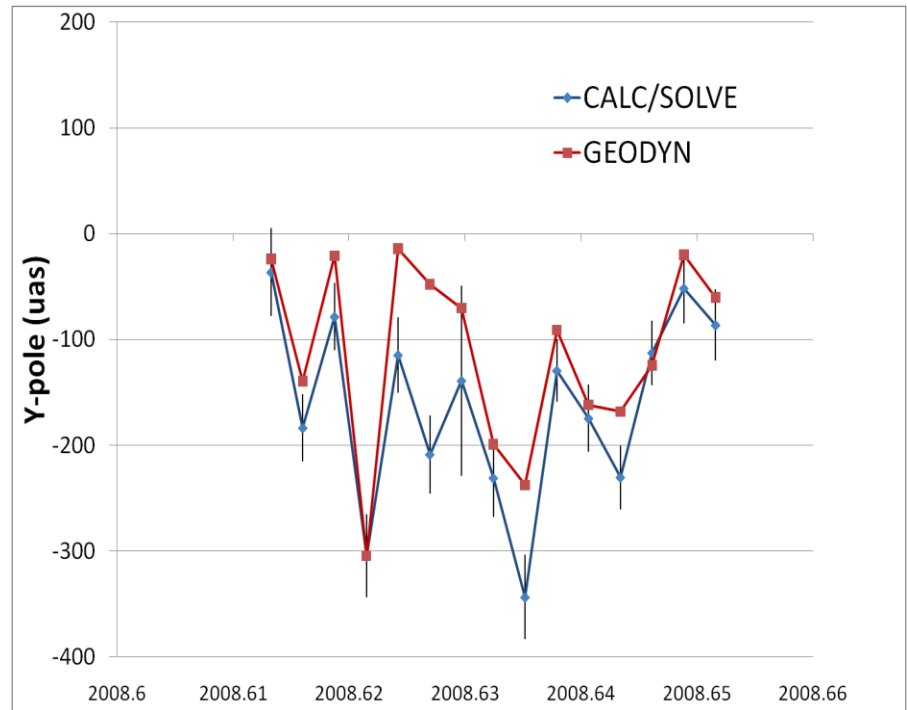
# Calc/Solve GEODYN Comparison



## CONT08



Station positions were fixed



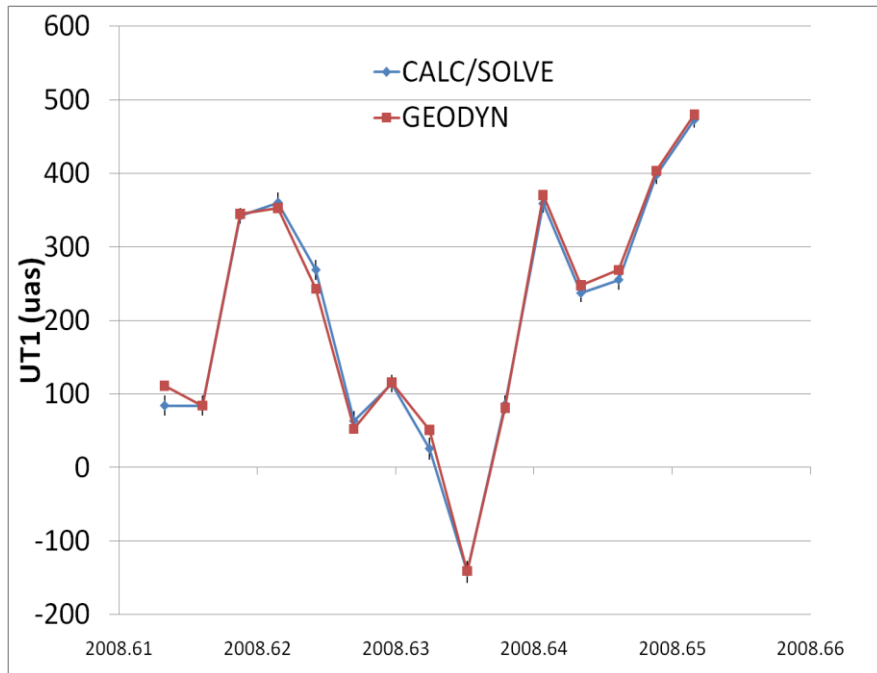
Station positions were also estimated



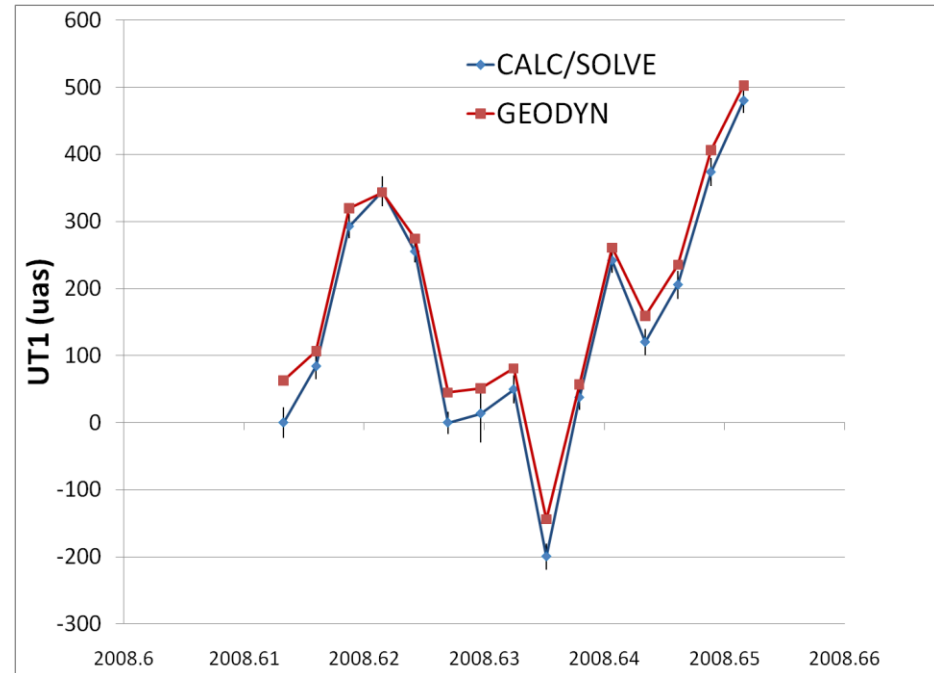
# Calc/Solve GEODYN Comparison



CONT08



Station positions were fixed



Station positions were also estimated



# SLR and VLBI GEODYN Solutions



1. Develop Normal equations for SLR data & VLBI data Using GEODYN for 2007-2008.
2. SLR processing uses Lageos1, Lageos2, Starlette, Stella, processed in 7-day arcs.
3. A single combined technique-specific normal equation is created to solve for EOP's from 2007-2008.
4. We have taken care to apply the same models to process both sets of data (e.g. pole tide, ocean loading with GOT4.7, Tidal EOP & COM). VLBI-session-specific parameters (troposphere and clocks) are adjusted separately and backsubstituted



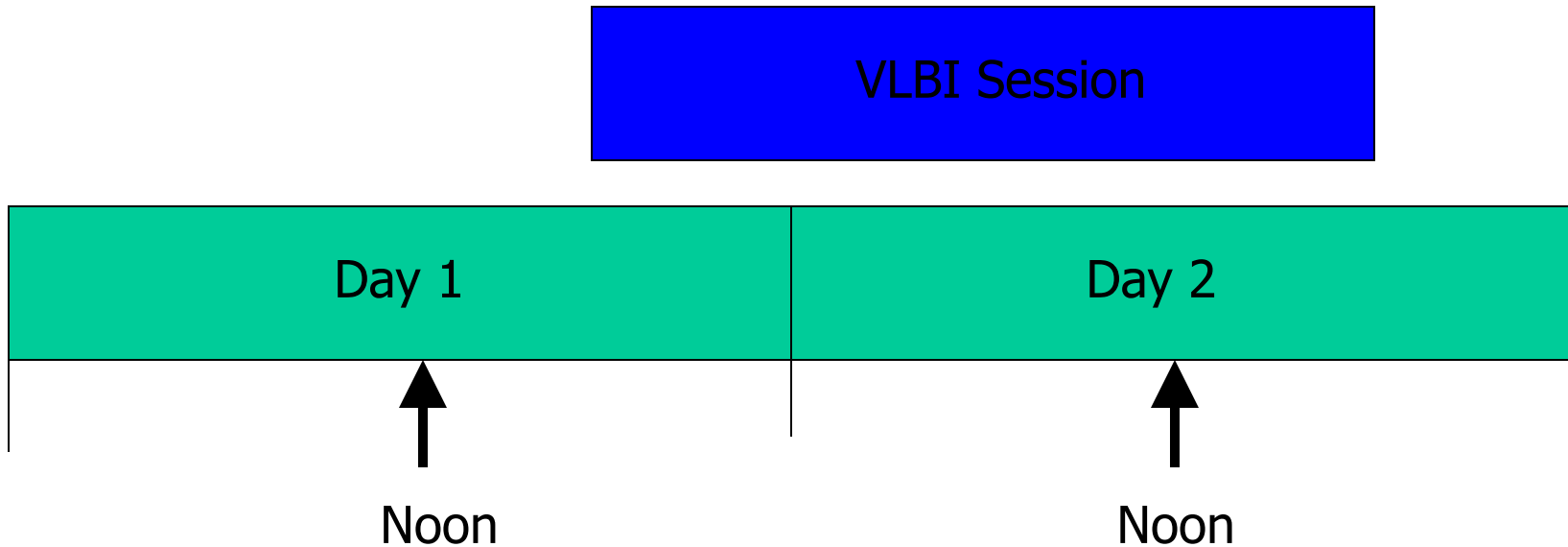
# SLR and VLBI GEODYN Solutions



1. At first, only EOP adjusted so as to compare results and intercompare the GEODYN processing of the two space geodetic techniques. *A priori* coordinates are in ITRF2005 (VLBI) & LPOD2005 (derived from ITRF2005 for SLR sites: adjusted scale, add missing sites, add data from 1983-1992)
2. The results are compared with IERSC04; All GEODYN solutions are daily values at 12:00 UT.
3. Daily EOP epochs at 12:00 UT are not necessarily optimum for VLBI, as sessions have different time boundaries.
  - EOP is estimated for 2 noon epochs for each VLBI session



# SLR and VLBI GEODYN Solutions



Each 24-hour VLBI session contributes to two Noon epochs of EOP estimation



# SLR and VLBI GEODYN Solutions



<b>Series</b>	<b>npts</b>	<b>Edit (mas)</b>	<b>RMS EOPx (mas)</b>	<b>Avg EOPx (mas)</b>	<b>RMS EOPy (mas)</b>	<b>Avg EOPy (mas)</b>
VLBI Geodyn Noon	422	1	0.217	-0.033	0.251	-0.024
VLBI Geodyn Midpoint	272	1	0.203	0.044	0.203	-0.039
VLBI Calc/Solve Midpoint	278	2	0.132	-0.049	0.131	0.022

DIFFERENCES RELATIVE TO IERS C04





# SLR and VLBI GEODYN Solutions



<b>Series</b>	<b>npts</b>	<b>Edit (mas)</b>	<b>RMS EOPx (mas)</b>	<b>Avg EOPx (mas)</b>	<b>RMS EOPy (mas)</b>	<b>Avg EOPy (mas)</b>
B. 4SLR (L1,L2+ Starlette+ Stella)	714	1	0.245	----	0.236	----
D. VLBI	433	1	0.212	----	0.247	----
E. VLBI+SLR	678	1	0.215	----	0.237	----

DIFFERENCES RELATIVE TO IERS C04



## Conclusions



1. GEODYN and CALC/SOLVE parameter estimates for 24-hour VLBI sessions mostly agree at about the 1-formal sigma level :  $\sim 50 \mu\text{s}$  wrms for EOP.
2. More investigation is required to understand discrepancies between CALC/SOLVE and GEODYN when site positions are estimated along with EOP in independent 24-hour session solutions
3. RMS EOP differences between C04 and GEODYN SOLVE VLBI solutions are 1.5 times greater than for standard VLBI solutions --- Need to resolve this.
4. We need to investigate the optimal strategy for combining VLBI and SLR normal equations – considering e.g. ground ties and solution weighting
5. Add GPS and DORIS in the combination