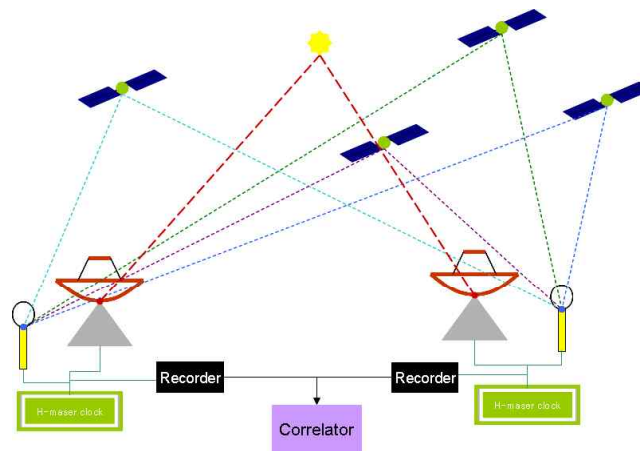


# THE FIRST EXPERIMENT WITH VLBI-GPS HYBRID SYSTEM



*Kwak, Y.<sup>1,2</sup>, Kondo, T.<sup>1,3</sup>, Gotoh, T.<sup>3</sup>, Amagai, J.<sup>3</sup>, Takiguchi, H.<sup>3</sup>,  
Sekido, M.<sup>3</sup>, Ichikawa, R.<sup>3</sup>, Sasao, T.<sup>4</sup>, Cho, J.<sup>2</sup>, Kim, T.<sup>1</sup>*

<sup>1</sup> Ajou University, Rep. of Korea

<sup>2</sup> Korea Astronomy and Space Science Institute, Rep. of Korea

<sup>3</sup> National Institute of Information and Communications Technology, Japan

<sup>4</sup> Yaeyama Star Club, Japan

# Motivation

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- ◎ In VLBI geodesy

Water vapor + clock = Arch-enemy

How to defeat?

- Observing as **many sources** as possible within a session
  - Many VLBI antennas(Radio Telescopes) at the same site
  - **Combined system with other space geodetic tech.**

# Motivation

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- ◎ A problem in Combination
  - Systematic errors b.t.w. different systems

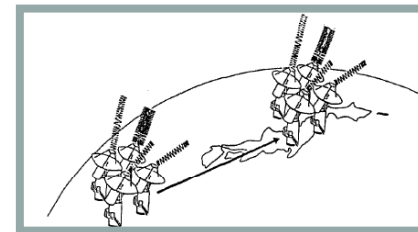
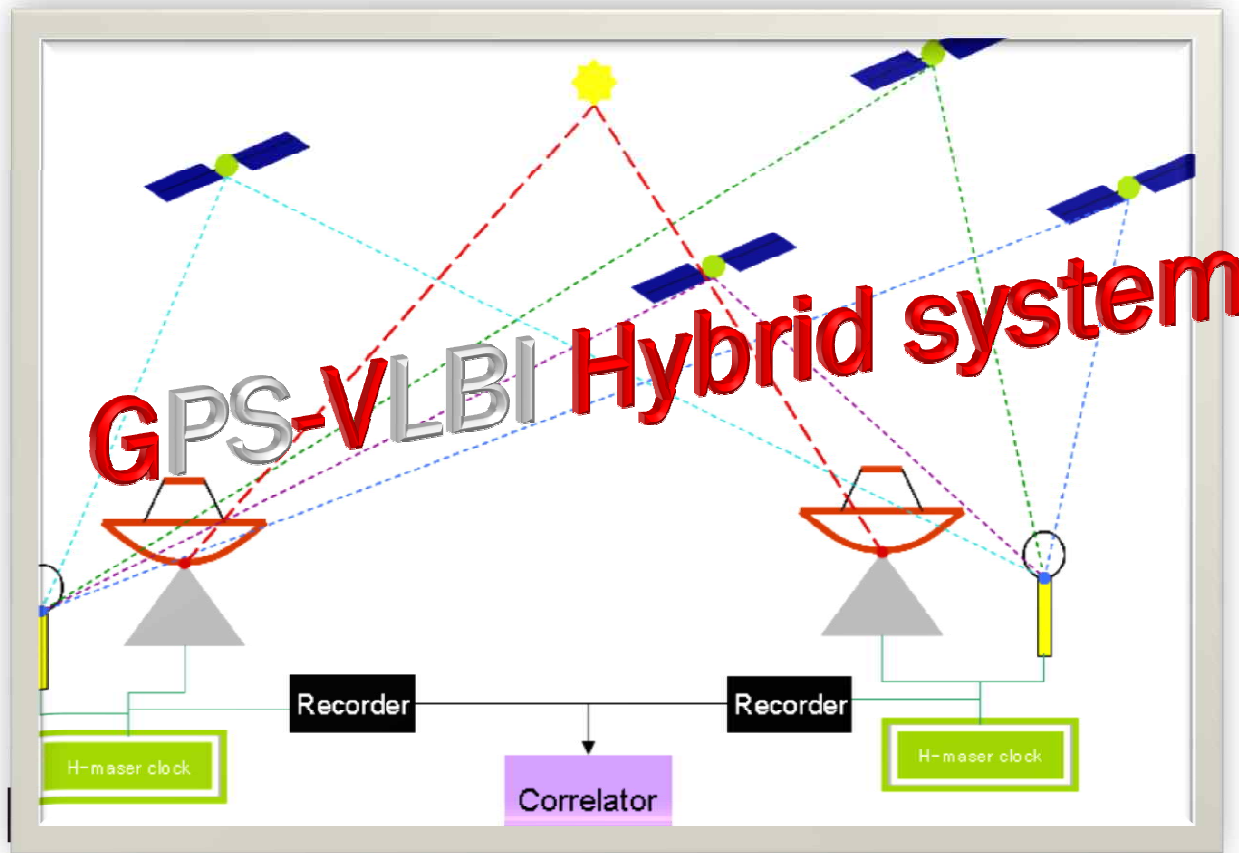
## ➤ Solution

**Sources** should be observed, and every data should be analyzed in as **common** method as possible.

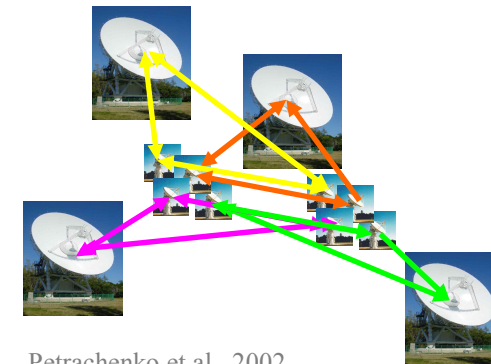
# Concept

## VLBI and GPS combination in observation level

A kind of multi-beam VLBI, observing quasars and GPS satellites at the **same site**, at the **same period** of time, and with **identical H-maser clock**.



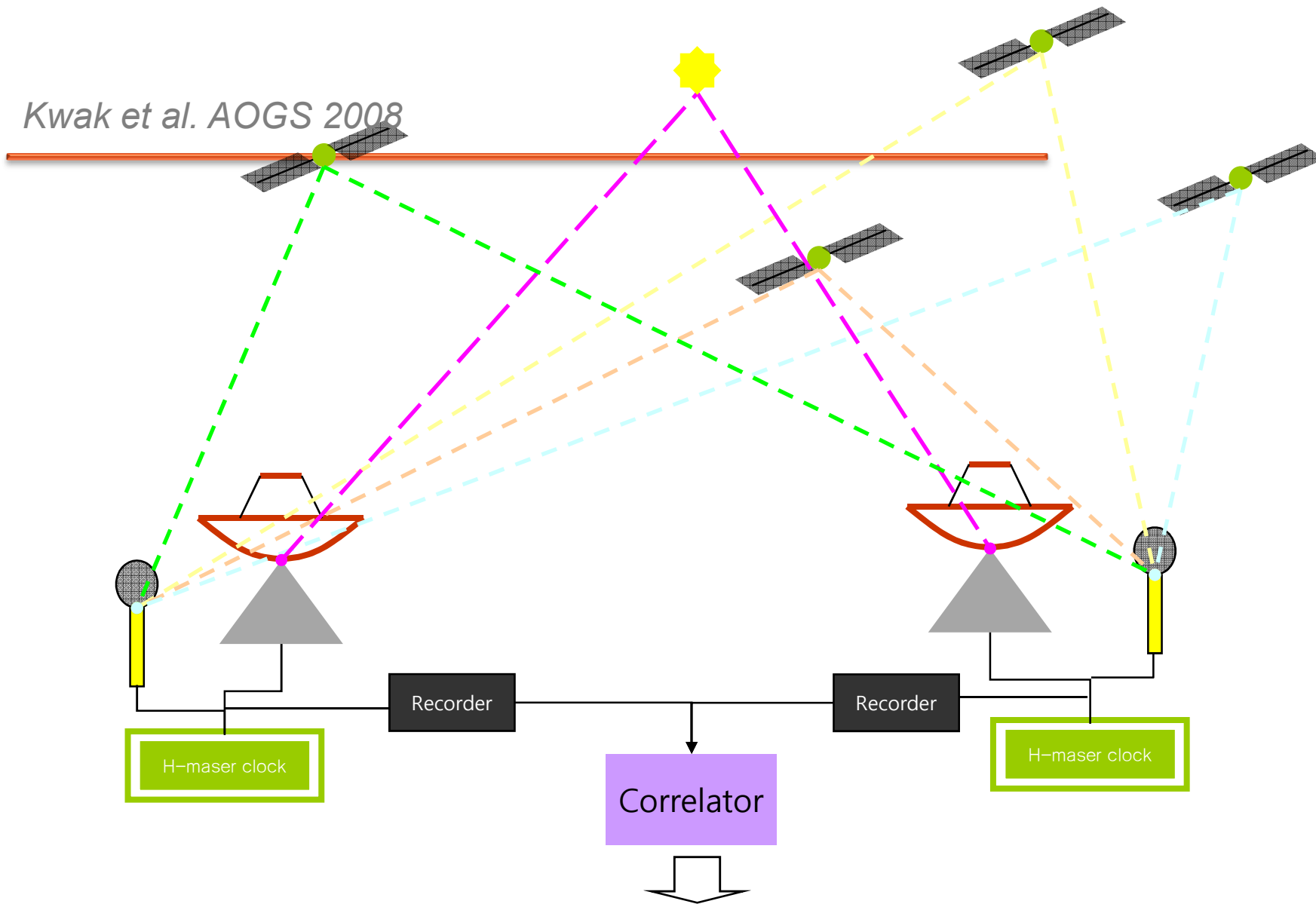
Sasao and Morimoto, 1991



Petrachenko et al., 2002

VLBI2010  
Observing Strategies

Kwak et al. AOGS 2008



Group delay (Quasars)  
Group delay (GPS satellites)

# GPS-VLBI HYBRID SYSTEM

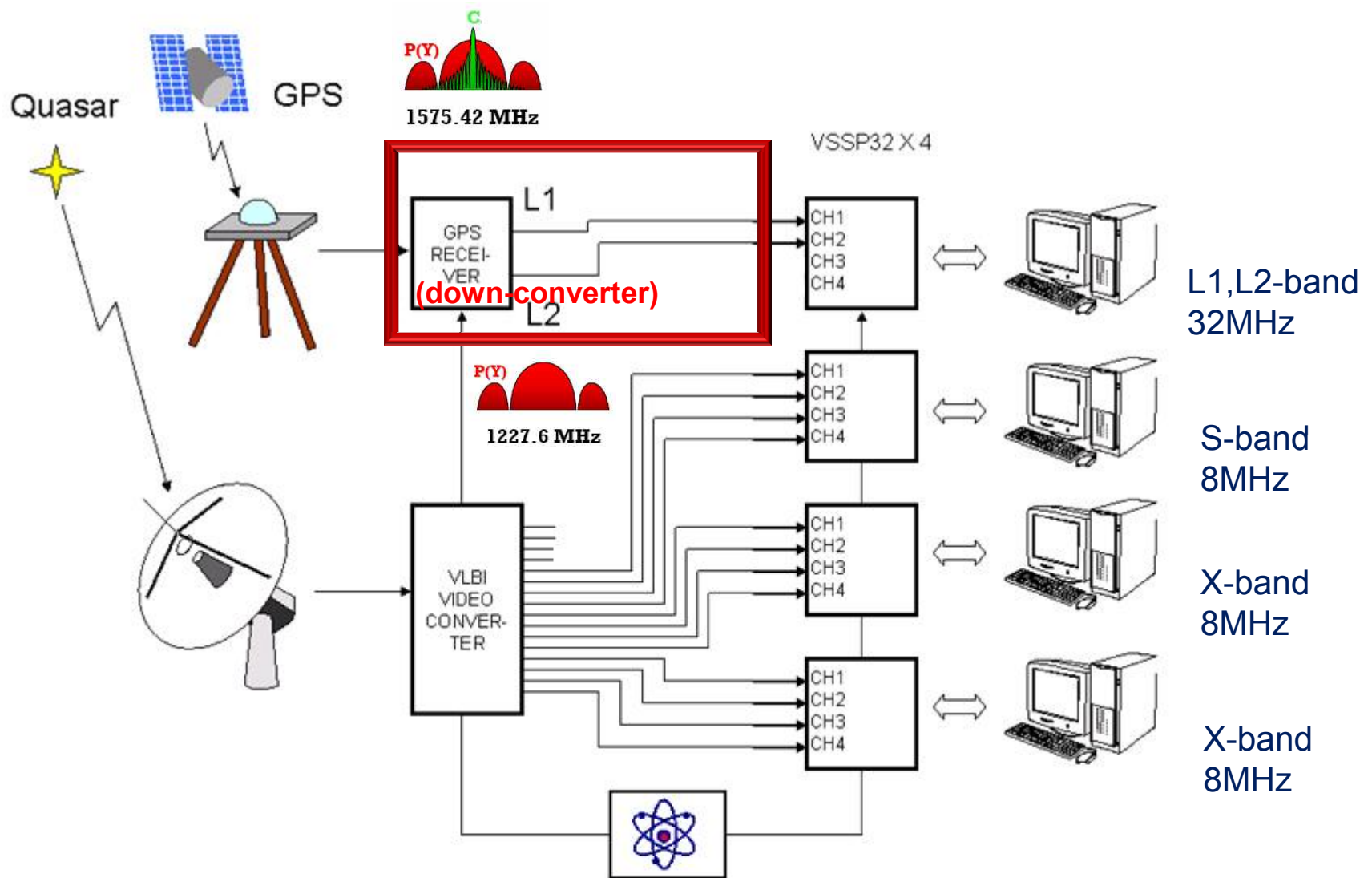
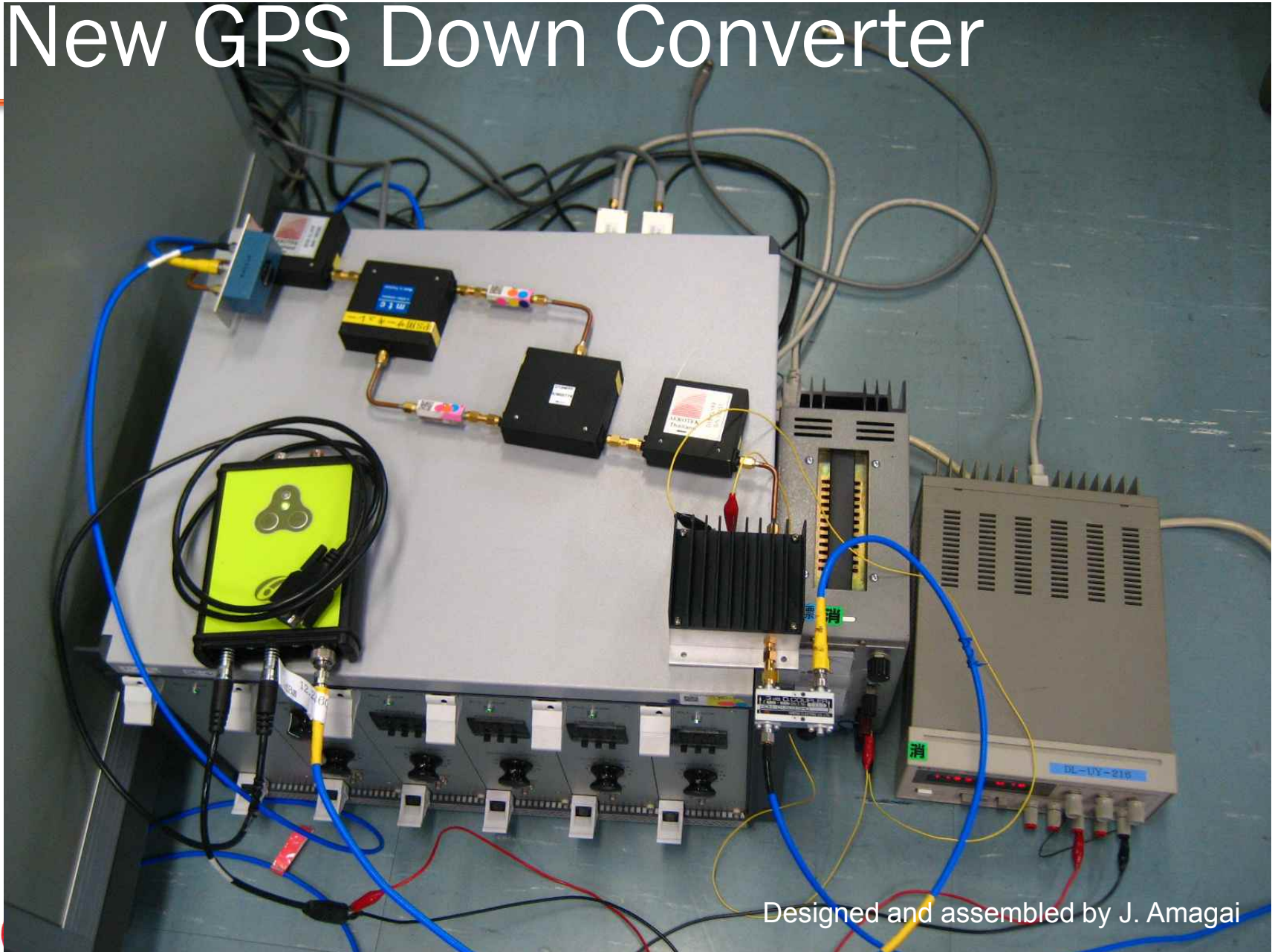


Figure 1. Schematic Block Diagram of Data Acquisition System

Revised from T. Kondo's diagram

# New GPS Down Converter



Designed and assembled by J. Amagai

# Estimation of Raw Data Volume for 24 Hrs.

	VLBI	GPS
Bandwidth / ch.	8MHz	32MHz
Number of channels	12ch	2ch
	(Hybrid case)	
Bit number	1bit/sample	1bit/sample
Observation duration	~ 30,000sec	86,400sec
Recording rate	384Mbits/sec	256Mbits/sec
Data volume		
	1.4TB	2.8TB
/ 24 hrs obs.		
Necessary HDD volume		
	480GB	<b>2.8TB</b>
/ pc		





# GPS-VLBI Hybrid Observation

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- ⊙ Normal VLBI 24hr session +
- ⊙ To reduce GPS data volume to 1/3
  - GPS Observation schedule



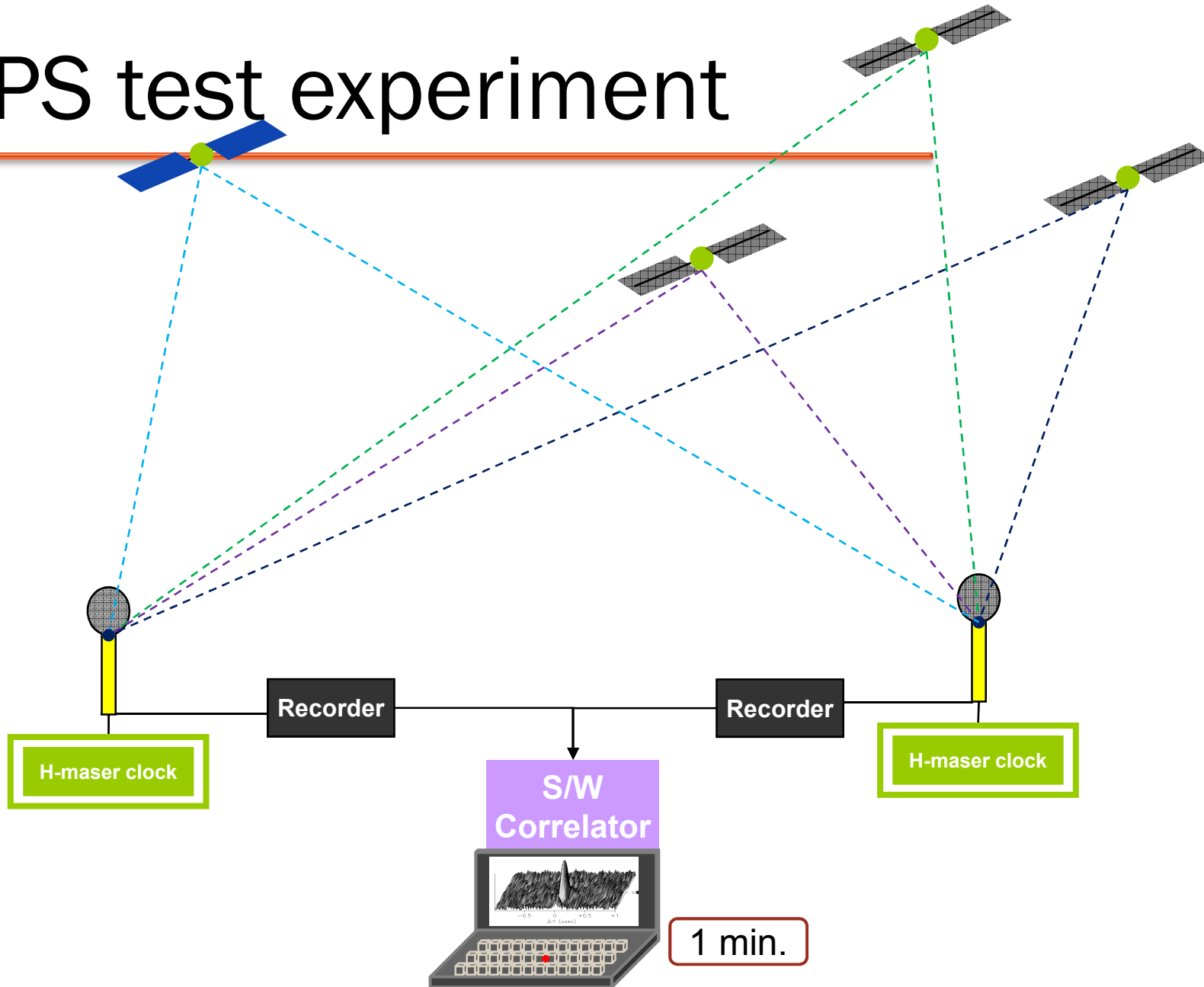
➤ Let's see how 1min. GPS Observation is

# GPS test experiment

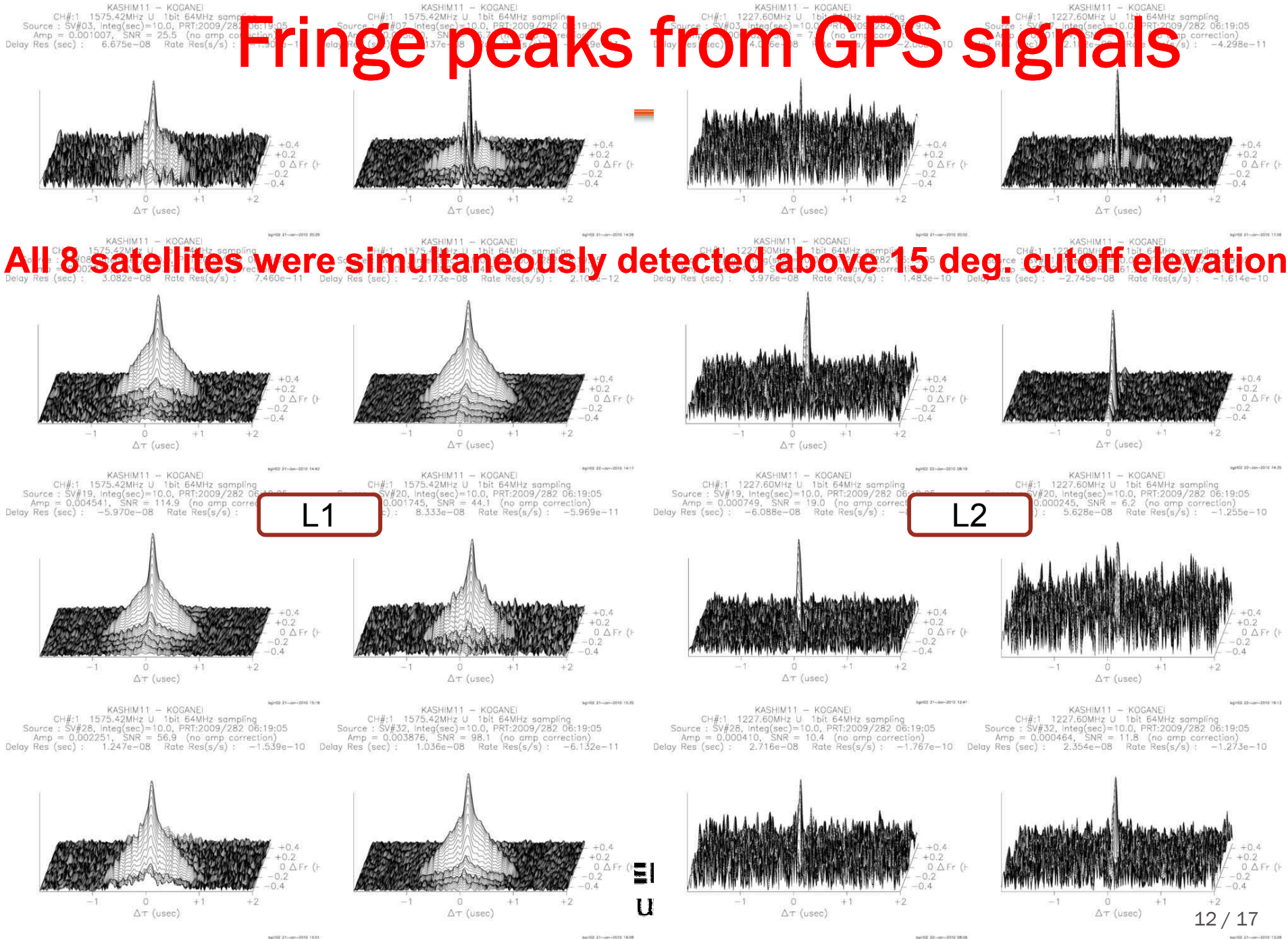
○ On 9<sup>th</sup> Oct. 2009



# GPS test experiment



# Fringe peaks from GPS signals

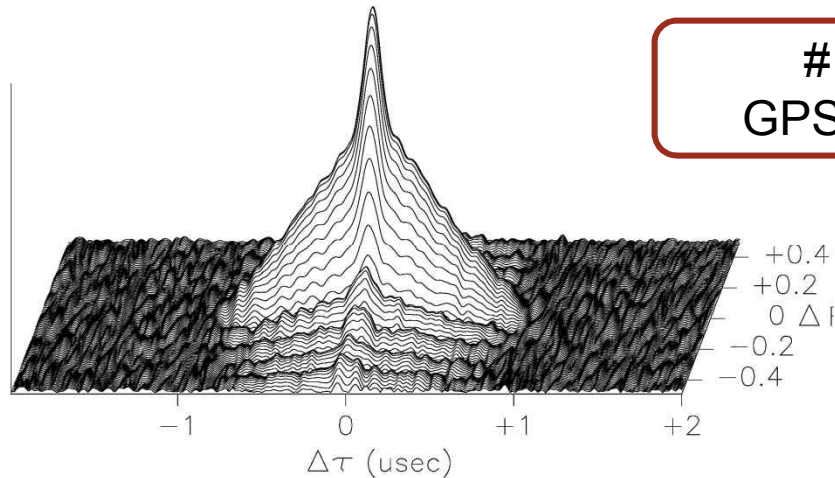


All 8 satellites were simultaneously detected above 15 deg. cutoff elevation

# Fringe peaks - best case

KASHIM11 - KOGANEI  
 CH#:1 1575.42MHz U 1bit 64MHz sampling  
 Source : SV#11, Integ(sec)=10.0, PRT:2009/282 06:19:05  
 Amp = 0.006100, SNR = 154.3 (no amp correction)  
 Delay Res (sec) : -2.173e-08 Rate Res(s/s) : 2.100e-1

KASHIM11 - KOGANEI  
 CH#:1 1227.60MHz U 1bit 64MHz sampling  
 Source : SV#11, Integ(sec)=10.0, PRT:2009/282 06:19:05  
 Amp = 0.002418, SNR = 61.2 (no amp correction)  
 Delay Res (sec) : -2.745e-08 Rate Res(s/s) : -1.614e-10



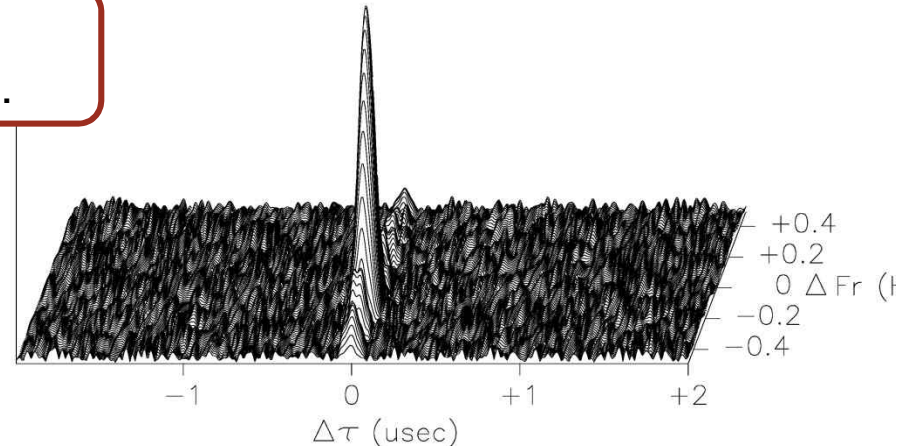
#11  
GPS Sat.

L1

S/N=154.3

~ 0.1 nsec  
~ 0.04 psec/sec

bgiri02 22-Jan-2



L2

S/N= 61.2

bgiri02 22-Jan-2010 14:31

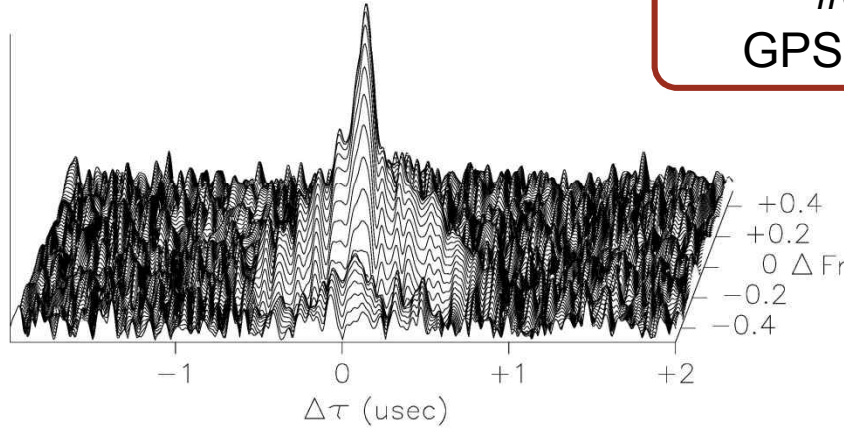
Elevation angle : 76.0° at Kashima 77.1° at Koganeei

# Fringe peaks – worst case

KASHIM11 – KOGANEI  
 CH#:1 1575.42MHz U 1bit 64MHz sampling  
 Source : SV#03, Integ(sec)=10.0, PRT:2009/282 06:19:05  
 Amp = 0.001007, SNR = 25.5 (no amp correction)  
 Delay Res (sec) : 6.675e-08 Rate Res(s/s) : -1.909e-10

KASHIM11 – KOGANEI  
 CH#:1 1227.60MHz U 1bit 64MHz sampling  
 Source : SV#03, Integ(sec)=10.0, PRT:2009/282 06:19:05  
 Amp = 0.000302, SNR = 7.6 (no amp correction)  
 Delay Res (sec) : 4.006e-08 Rate Res(s/s) : -2.008e-10

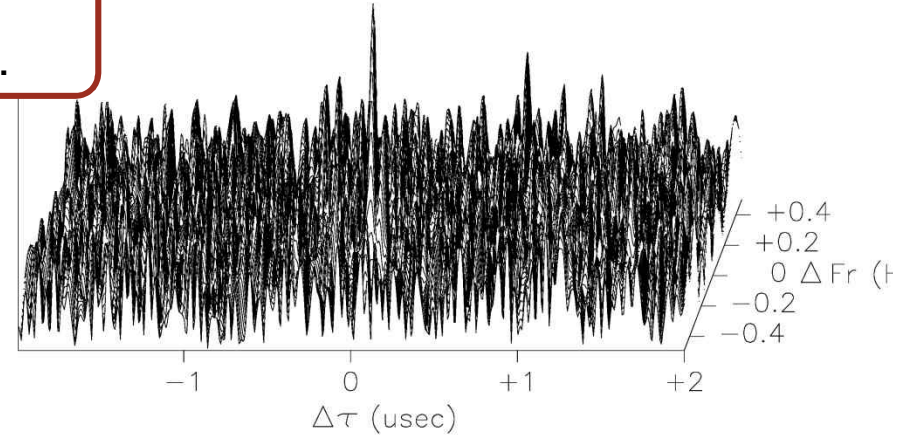
#3  
GPS Sat.



L1

S/N=25.5

bgjr02 21-Jan-2011



L2

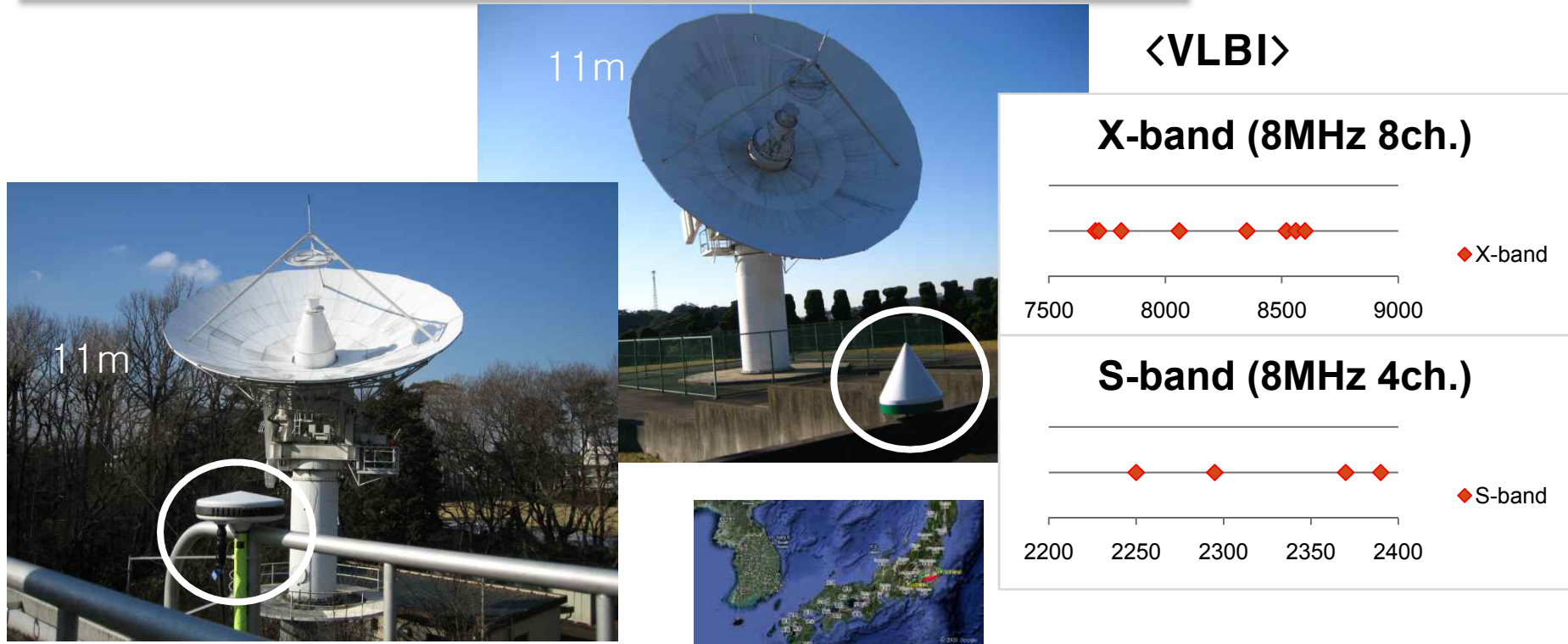
S/N= 7.6

bgjr02 21-Jan-2010 20:52

Elevation angle : 23.4° at Kashima 22.4° at KoganeI

# The First experiment with GV Hybrid System

- Now under Correlation Processing (generating a priories)



\$EXPER K09344

\$SOURCES

GPSALL \$ 01 21 41.59504260 11 49 50.4131870 2000.0 0.0 GLB1069

\$SKED

GPSALL 10 L PREOB 09344090000 60 M DOB 0 POSTOB R-G- 1F000000 1F000000 YYYN 60 60

GPSALL 10 L PREOB 09344090300 60 M DOB 0 POSTOB R-G- 1F000038 1F000038 YYYN 60 60

GPSALL 10 L PREOB 09344090600 60 M DOB 0 POSTOB R-G- 1F000046 1F000046 YYYN 60 60

# Conclusion

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- ◎ New GPS down-converter worked well and GPS signals were successfully sampled and recorded in VLBI system.
- ◎ Some data from GPS satellites satisfied VLBI precision in thermal noise errors
- ◎ Longer observation duration necessary



# Future Works

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- ◎ Test experiment data of G-V Hybrid system in December 2009 will be correlated and analyzed.
- ◎ Analysis S/W for GPS & VLBI Observation for consistency b.t.w. techniques.
- ◎ Larger network(global scale)
  - ➔ Tie GPS satellite to ICRF and determination of UT1